

Chapter 3

RTL Level Modeling with C++

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RTL Level Modeling with C/C++

- **RTL Principles**

- Elements of datapath
- Elements of control unit

- **Bus Communications**

- **Utility functions**

- **Bus operations**

- Array Attributes

- Logical Operations

- Adding Operations

- Relational Operations

- IO Operations

- **Basic Elements of RTL**

- Combinational Elements

- Registers and Counters

- Functional register
- dRegister
- dRegisterE
- dRegisterRaE
- upCounter
- upCounterRaE

- Memory Structure

- Controller FSM

- Controller 11011

- **RTL design example 1: LRU**

- LRU structure

- LRU Modeling

- Controller

- Ordered instantiation

- **RTL design example 2: Exponential Circuit**

- Exponential Circuit Datapath

- Exponential Circuit Controller

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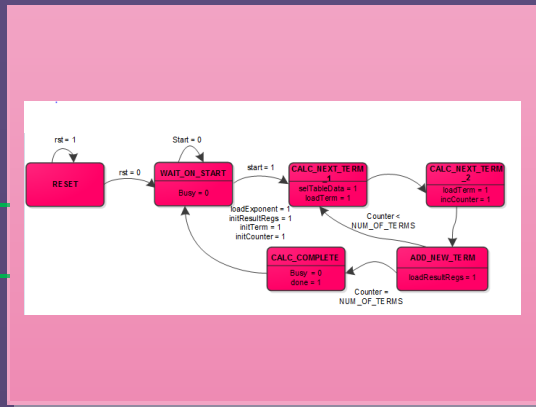
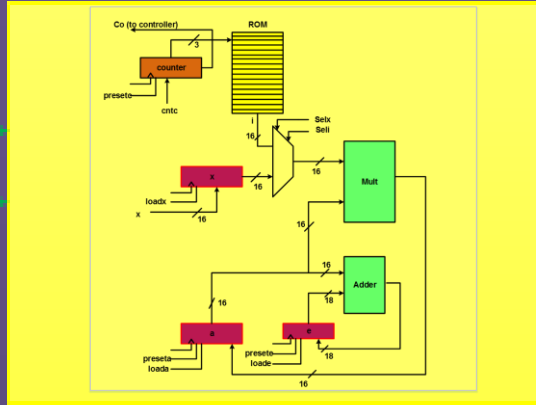
- RTL design example 2: Exponential Circuit

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RTL Principles

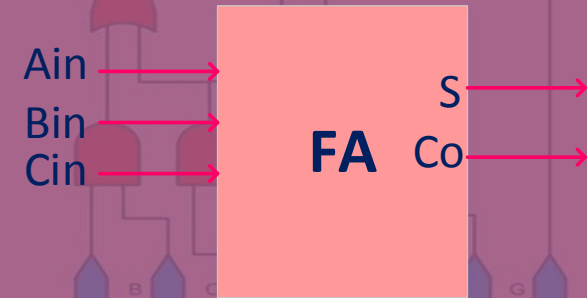
Elements of an RT level component



Elements of Datapath

- Combinational Components

- Adders
- Comparators
- Multiplexers
- ALUs



- Logical Operations

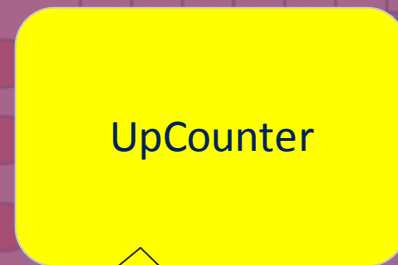
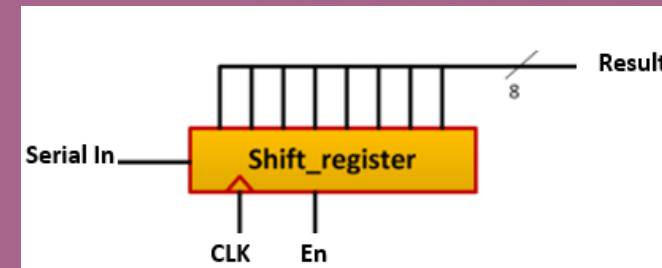
- Vector based
- Scalar operations
- Mixed

Elements of Datapath

- RTL internal buses
 - Unconstrained
 - Represent multi-value logic system

Sequential component

- Registers
- Registers with some functionality
- Register files

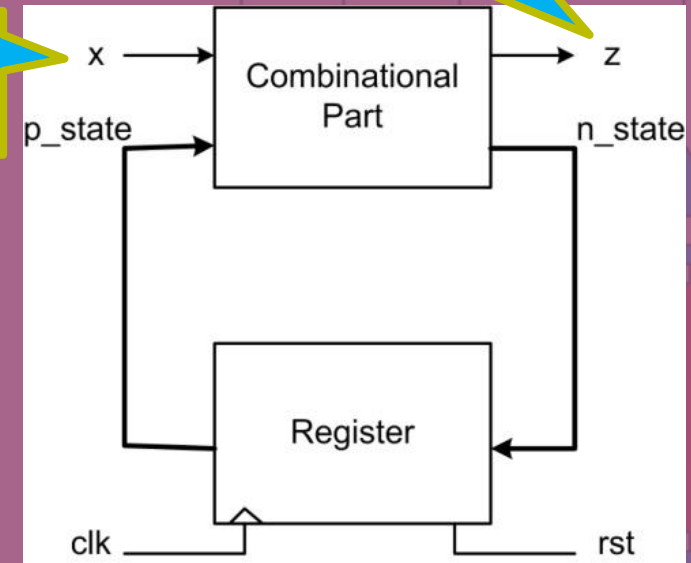
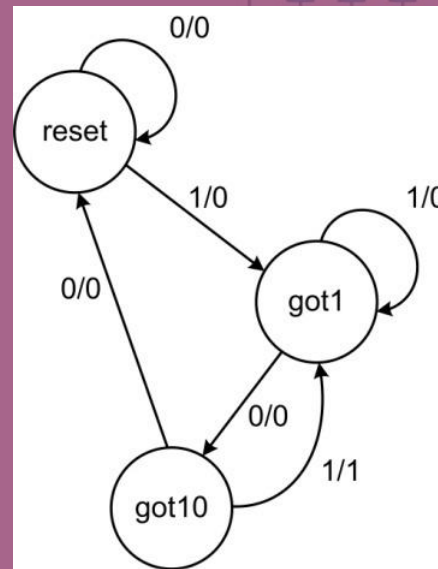


Elements of Control Unit

- One or more state machines
 - Huffman style

Inputs from datapath
or external

Control signals



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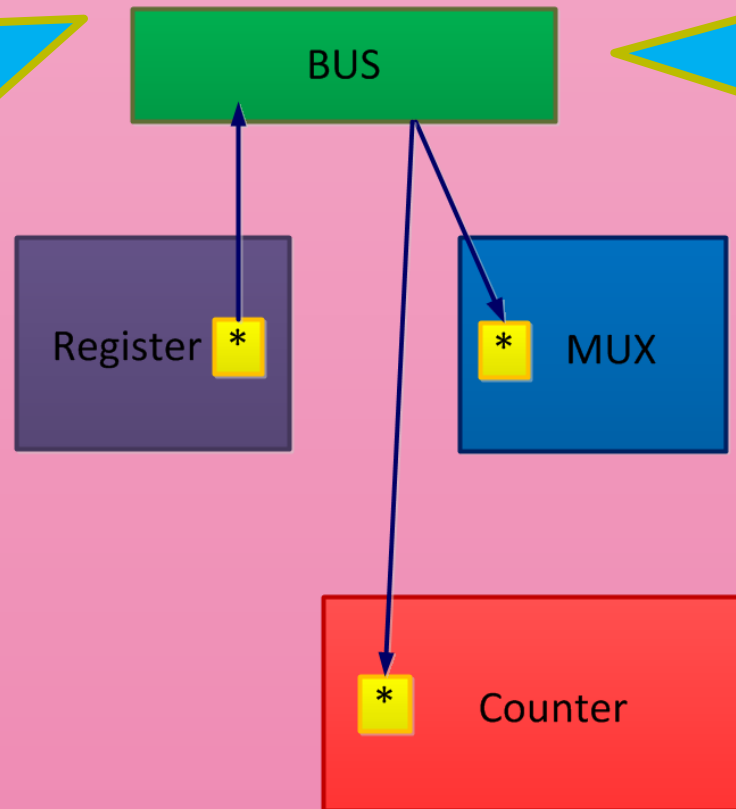
- **RTL design example 2: Exponential Circuit**

- Exponential Circuit Datapath

- Exponential Circuit Controller

Bus Communications

As design abstraction approaches ESL, Role of communication become more pronounced in the design and hardware description



In order to have consistent set of communication lines between datapath and controller, the same type of bus should be used for both

Bus Communications

- Bus owns data
- Components look up for data
- Operators are overloaded

$A_{bus} = R_{bus} + B_{bus}$
 $A_{bus} = R_{bus} \& B_{bus}$
 $A_{bus} = R_{bus} | B_{bus}$

Bus Communications

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  (Global Scope)
1  #include <iostream>
2  #include "utilityFunctions.h"
3  #include <string>
4  using namespace std;
5
6  #define MIN(a,b) ((a<b)?a:b);
7  #define MAX(a,b) ((a>b)?a:b);
8
9  class bus{
10     string v;
11 public:
12     bus() { v.resize(1, 'X'); }
13     bus(int SIZE) { v.resize(SIZE, 'X'); }
14     bus(int SIZE, char c) { v.resize(SIZE, c); }
15     bus(const string& s) { v = s; }
16     bus(const char* c) { v = c; }
17     bus(const bus& a) { v = a.v; } // Copy constructor for =
18
19     bus range(int i1, int i2){ ... }
20
21     bus at(int i){ ... }
22
23     char operator[](int i) const { ... }
24
25     char& operator[](int i){ ... }
26
27     int length(){ ... }
28
29     void fill(char c){ ... }
30
31     friend bus operator& (bus a, bus b){ ... }
32
33     friend bus operator| (bus a, bus b){ ... }
34
35     friend bus operator^ (bus a, bus b){ ... }
36
37     friend bus operator~ (bus a){ ... }
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```

classVectorPrimitives.h

String member variable for its logical data

Bus-arrays for multi-bit datapath buses and control unit vector while 1-bit buses for Controller signals, one-bit datapath signal and control unit internal wires.

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- Exponential Circuit Datapath

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Utility Functions

```
classVectorPrimitives.h  classVectorFunctions.h  classVectorPrimitives.cpp  utilityFunctions.h  X
RTL Description  (Global Scope)
1 char and(char a, char b);
2 char or(char a, char b);
3 char not(char a);
4 char tri(char a, char c);
5 char resolve(char a, char c);
6 char xor(char a, char b);
7
8 void fullAdder(char a, char b, char ci, char& co, char& sum);
9
```

utilityFunctions.h

The bus class we use for our interconnection uses string variable.

Why char?

1. Char Is the best for representation of various logic values
2. Compatibility with c++ string class

Shortcoming?

Lack of logical operation

Utility Functions

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp  X
```

RTL Description (Global Scope)

```
1 char and(char a, char b)
2 {
3     if ((a == '0') || (b == '0')) return '0';
4     else if ((a == '1') && (b == '1')) return '1';
5     else return 'X';
6 }
7
8 char or(char a, char b) { ... }
14
15 char not(char a) { ... }
21
22 char tri(char a, char c)
23 {
24     if (c == '1') return a;
25     else return 'Z';
26 }
27
28 char resolve(char a, char b)
29 {
30     if (a == 'Z' || a == b) return b;
31     else if (b == 'Z') return a;
32     else return 'X';
33 }
34
35 char xor(char a, char b) { ... }
41
42 void fullAdder(char a, char b, char ci, char & co, char & sum)
43 {
44     char axb, ab, abc;
45
46     axb = xor(a, b);
47     ab = and(a, b);
48     abc = and(axb, ci);
49     co = or(ab, abc);
50     sum = xor(axb, ci);
51 }
52
```

utilityFunctions.cpp

Full adder implementation using primitives

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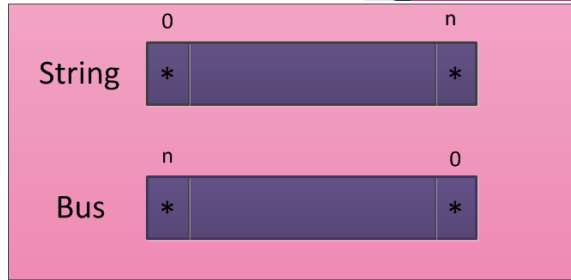
Array Attributes

```
classVectorPrimitives.h  classVectorFunctions.h  utilityFunctions.h  utilityFunctions.cpp
RTL Description  (Global Scope)
19 bus range(int i1, int i2)
20 {
21     int left = MAX(i1, i2);
22     int rite = MIN(i1, i2);
23     bus slice(left-rite, 'X');
24     int vSize = v.length();
25     slice.v = v.substr(vSize - left, vSize - rite);
26     return slice;
27 }
28
29 bus at(int i)
30 {
31     bus bit(1, 'X');
32     int vSize = v.length();
33     bit.v = v.at(vSize - 1 - i);
34     return bit;
35 }
36
37 char operator[](int i) const { ... }
40
41 char& operator[](int i) { ... }
44
45 int length() { ... }
49
50 void fill(char c) { ... }
54
55 friend bus operator& (bus a, bus b) { ... }
69
70 friend bus operator| (bus a, bus b) { ... }
84
85 friend bus operator^ (bus a, bus b) { ... }
99
100 friend bus operator~ (bus a) { ... }
111
112 friend bus operator+ (const bus a, const bus b)
113 {
114     int aSize = a.v.length();
```

classVectorPrimitives.h

Bus slicing

String uses 0 for its left character but range takes the larger index for left character



Array Attributes

```
classVectorPrimitives.h  classVectorFunctions.h  utilityFunctions.h  utilityFunctions.cpp
RTL Description  (Global Scope)
19  bus range(int i1, int i2)
20  {
21      int left = MAX(i1, i2);
22      int rite = MIN(i1, i2);
23      bus slice(left-rite, 'X');
24      int vSize = v.length();
25      slice.v = v.substr(vSize - left, vSize - rite);
26      return slice;
27  }
28
29  bus at(int i)
30  {
31      bus bit(1, 'X');
32      int vSize = v.length();
33      bit.v = v.at(vSize - 1 - i);
34      return bit;
35  }
36
37  char operator[](int i) const { ... }
40
41  char& operator[](int i) { ... }
44
45  int length() { ... }
49
50  void fill(char c) { ... }
54
55  friend bus operator& (bus a, bus b) { ... }
69
70  friend bus operator| (bus a, bus b) { ... }
84
85  friend bus operator^ (bus a, bus b) { ... }
99
100 friend bus operator~ (bus a) { ... }
111
112 friend bus operator+ (const bus a, const bus b)
113 {
114     int aSize = a.v.length();
```

classVectorPrimitives.h

```
29  bus at(int i)
30  {
31      bus bit(1, 'X');
32      int vSize = v.length();
33      bit.v = v.at(vSize - 1 - i);
34      return bit;
35  }
```

Bus indexing

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Array Attributes

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  bus  range(int i1, int i2)
28  bus at(int i) { ... }
29
36
37  char operator[](int i) const {
38      return v[v.length()-i-1];
39  }
40
41  char& operator[](int i) {
42      return v[v.length()-i-1];
43  }
44
45  int length() { ... }
49
50  void fill(char c) { ... }
54
55  friend bus operator& (bus a, bus b) { ... }
69
70  friend bus operator| (bus a, bus b) { ... }
84
85  friend bus operator^ (bus a, bus b) { ... }
99
100  friend bus operator~ (bus a) { ... }
111
112  friend bus operator+ (const bus a, const bus b) { ... }
141
142  friend bus operator, (bus a, bus b) { ... }
157
158  friend bool operator== (bus a, const bus b) { ... }
162
163  friend bool operator> (bus a, const bus b) { ... }
178
179  friend bool operator< (bus a, const bus b) { ... }
194
195  bool operator&& (bus b) { ... }
211
212  bool operator|| (bus b) { ... }
228
```

It returns char type instead of bus type in at()

Bracket overloading for using indexing on the left hand side

classVectorPrimitives.h

Array Attributes

```
classVectorPrimitives.h  classVectorFunctions.h  utilityFunctions.h  utilityFunctions.cpp
RTL Description  (Global Scope)
28
29 bus at(int i){...}
36
37 char operator[](int i) const {...}
40
41 char& operator[](int i){...}
44
45 int length()
46 {
47     return v.length();
48 }
49
50 void fill(char c)
51 {
52     v.assign(v.length(), c);
53 }
54
55 friend bus operator& (bus a, bus b){...}
69
70 friend bus operator| (bus a, bus b){...}
84
85 friend bus operator^ (bus a, bus b){...}
99
100 friend bus operator~ (bus a){...}
111
112 friend bus operator+ (const bus a, const bus b){...}
138
139 friend bus operator, (bus a, bus b){...}
154
155 friend bool operator== (bus a, const bus b){...}
159
160 friend bool operator> (bus a, const bus b){...}
175
176 friend bool operator< (bus a, const bus b){...}
191
192 friend ostream& operator<<(ostream& out, const bus a){...}
196
```

classVectorPrimitives.h

Fill the bus with its character argument

Logical Operations

Declared as friends inside the bus class

```
140 friend bus operator~ (bus a) { ... }
141
142 friend bus operator+ (const bus a, const bus b) { ... }
143
144 friend bus operator, (bus a, bus b) { ... }
145
157 friend bool operator== (bus a, const bus b) { ... }
158
162 friend bool operator> (bus a, const bus b) { ... }
163
178 friend bool operator< (bus a, const bus b) { ... }
179
194
```

classVectorPrimitives.h

Logical Operations

```
classVectorPrimitives.h  classVectorFunctions.h  utilityFunctions.h  utilityFunctions.cpp
RTL Description  bus
50 void fill(char c) { ... }
54
55 friend bus operator& (bus a, bus b)
56 {
57     int aSize = a.v.length();
58     int bSize = b.v.length();
59     int rSize;
60     if (bSize == 1) rSize = aSize; else rSize = MIN(aSize, bSize);
61     bus r(rSize, 'X');
62     int i;
63     for (i = rSize - 1; i >= 0; i--) {
64         if (bSize == 1) r.v[i] = and(a.v.at(i), b.v.at(0));
65         else r.v[i] = and(a.v.at(i), b.v.at(i));
66     }
67     return r;
68 }
69
70 friend bus operator| (bus a, bus b) { ... }
71
72 friend bus operator^ (bus a, bus b)
73 {
74     int aSize = a.v.length();
75     int bSize = b.v.length();
76     int rSize;
77     if (bSize == 1) rSize = aSize; else rSize = MIN(aSize, bSize);
78     bus r(rSize, 'X');
79     int i;
80     for (i = rSize - 1; i >= 0; i--) {
81         if (bSize == 1) r.v[i] = xor(a.v.at(i), b.v.at(0));
82         else r.v[i] = xor(a.v.at(i), b.v.at(i));
83     }
84     return r;
85 }
86
87 friend bus operator~ (bus a) { ... }
88
89 friend bus operator+ (const bus a, const bus b) { ... }
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```

Size fixing

Overloading & operator for bus

classVectorPrimitives.h

Adding Operations

```
SeqDetector.cpp  utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h  classVectorFunctions.h
RTL Description  bus
111
112 friend bus operator+ (const bus a, const bus b)
113 {
114     int aSize = a.v.length();
115     int bSize = b.v.length();
116     int rSize;
117     int min = MIN(aSize, bSize);
118     if (bSize == 1) rSize = aSize; else rSize = min + 1;
119     bus r(rSize, 'X');
120
121     char ci('0');
122     char co('0') sum('0');
123     if (bSize == 1){
124         for (int i = rSize - 1; i >= 0; i--) {
125             if (i == rSize - 1) fullAdder(a.v.at(i), b.v.at(0), ci, co, sum);
126             else fullAdder(a.v.at(i), '0', ci, co, sum);
127             ci = co;
128             r.v[i] = sum;
129         }
130     }
131     else {
132         for (int i = rSize - 1; i >= 1; i--) {
133             fullAdder(a.v.at(i - 1), b.v.at(i - 1), ci, co, sum);
134             ci = co;
135             r.v[i] = sum;
136         }
137         r.v[0] = co;
138     }
139     return r;
140 }
141
142 friend bus operator, (bus a, bus b) { ... }
143
144 friend bool operator== (bus a, const bus b) { ... }
145
146 friend bool operator> (bus a, const bus b) { ... }
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```

classVectorPrimitives.h

String indexing

Overloading + operator using full adder

Logical Operations

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  bus
54
55 friend bus operator& (bus a, bus b){ ... }
69
70 friend bus operator| (bus a, bus b){ ... }
84
85 friend bus operator^ (bus a, bus b){ ... }
99
100 friend bus operator~ (bus a){ ... }
111
112 friend bus operator+ (const bus a, const bus b){ ... }
141
142 friend bus operator, (bus a, bus b)
{
    int aSize = a.v.length();
    int bSize = b.v.length();
    int rSize = aSize + bSize;
    bus r(rSize, 'X');
    int i;
    for (i = bSize - 1; i >= 0; i--) {
        r.v[aSize + i] = b.v.at(i);
    }
    for (i = aSize - 1; i >= 0; i--) {
        r.v[i] = a.v.at(i);
    }
    return r;
}
158 friend bool operator== (bus a, const bus b){ ... }
162
163 friend bool operator> (bus a, const bus b){ ... }
178
179 friend bool operator< (bus a, const bus b){ ... }
194
195 bool operator&& (bus b){ ... }
211
212 bool operator|| (bus b){ ... }
228
```

classVectorPrimitives.h

Overloading concatenation operator

Rational Operations

```
LRUdesignn.cpp  classVectorPrimitives.cpp  classVectorPrimitives.h  registersTB.cpp  RTLevelTB.cpp
RTL Description  bus
158 friend bool operator==(bus a, const bus b)
159 {
160     return (a.v == b.v);
161 }
162 friend bool operator> (bus a, const bus b) // Assume same size
163 {
164     int aSize = a.v.length();
165     int bSize = b.v.length();
166     bool r = false;
167     int i = 0;
168     do{
169         if ((a.v[i] == '1') && (b.v[i] == '0')){
170             r = true; break;
171         }
172         else if ((a.v[i] == '0') && (b.v[i] == '1')){
173             r = false; break;
174         }
175     } while (++i < aSize);
176     return r;
177 }
178 friend bool operator< (bus a, const bus b) // Assume same size
179 {
180     int aSize = a.v.length();
181     int bSize = b.v.length();
182     bool r = false;
183     int i = 0;
184     do{
185         if ((a.v[i] == '0') && (b.v[i] == '1')){
186             r = true; break;
187         }
188         else if ((a.v[i] == '1') && (b.v[i] == '0')){
189             r = false; break;
190         }
191     } while (++i < aSize);
192     return r;
193 }
194
```

classVectorPrimitives.h

Logical Operations

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  bus
163  friend bool operator> (bus a, const bus b){ ... }
178
179  friend bool operator< (bus a, const bus b){ ... }
194
195  bool operator&& (bus b) // Must be member function for second a
196  {
197      int aSize = this->v.length();
198      int bSize = b.v.length();
199      int rSize;
200      if (bSize == 1) rSize = aSize; else rSize = MIN(aSize, bSize);
201      bool r = false;
202      char c = '0';
203      int i;
204      for (i = rSize - 1; i >= 0; i--) {
205          if (bSize == 1) c = and(this->v.at(i), b.v.at(0));
206          else c = and(this->v.at(i), b.v.at(i));
207          if (c == '1') r = true;
208      }
209      return r;
210  }
211
212  bool operator|| (bus b)
213  {
214      int aSize = this->v.length();
215      int bSize = b.v.length();
216      int rSize;
217      if (bSize == 1) rSize = aSize; else rSize = MIN(aSize, bSize);
218      bool r = false;
219      char c = '0';
220      int i;
221      for (i = rSize - 1; i >= 0; i--) {
222          if (bSize == 1) c = or(this->v.at(i), b.v.at(0));
223          else c = or(this->v.at(i), b.v.at(i));
224          if (c == '1') r = true;
225      }
226      return r;
227  }
```

classVectorPrimitives.h

"this" is the pointer to the first operand

Member functions of the bus -> only one arguments is passed

Functions return true if contains at least one "1"

IO Operations

```
classVectorPrimitives.cpp  LRUdesignTB.cpp  LRUdesign.cpp  classVectorPrimitives.h
RTL Description  bus
100  friend bus operator~ (bus a){ ... }
111
112  friend bus operator+ (const bus a, const bus b){ ... }
141
142  friend bus operator, (bus a, bus b){ ... }
157
158  friend bool operator== (bus a, const bus b){ ... }
162
163  friend bool operator> (bus a, const bus b){ ... }
178
179  friend bool operator< (bus a, const bus b){ ... }
194
195  bool operator&& (bus b){ ... }
211
212  bool operator|| (bus b){ ... }
228
229  friend ostream& operator<<(ostream& out, const bus a)
230  {
231      return(out << a.v);
232  }
233
234  friend istream& operator>>(istream& in, bus& a)
235  {
236      return(in >> a.v);
237  }
238
239  int ival ()
240  {
241      int aSize = v.length();
242      int ia=0;
243      for (int i = aSize - 1; i >= 0; i--) {
244          if (v.at(i) == '1') ia = ia + int(pow(2, (aSize - 1 - i) ));
245      }
246      return ia;
247  }
248  void resize(int i, char c) { v.resize(i, c); }
249  };
```

classVectorPrimitives.h

friend ostream& operator<<(ostream& out, const bus a)
{
 return(out << a.v);
}

friend istream& operator>>(istream& in, bus& a)
{
 return(in >> a.v);
}

Because the first operand is not of the bus class, we need both arguments and so we use friend

RTL Level Modeling with C/C++

- **RTL Principles**

- Elements of datapath
- Elements of control unit

- **Bus Communications**

- **Utility functions**

- **Bus operations**

- Array Attributes

- Logical Operations

- Adding Operations

- Relational Operations

- IO Operations

- **Basic Elements of RTL**

- Combinational Elements

- Registers and Counters

- Functional register
- dRegister
- dRegisterE
- dRegisterRaE
- upCounter
- upCounterRaE

- Memory Structure

- Controller FSM

- Controller 11011

- **RTL design example: LRU**

- LRU structure

- LRU Modeling

- Controller

- Ordered instantiation

- **RTL design example 2: Exponential Circuit**

- Exponential Circuit Datapath

- Exponential Circuit Controller

Combinational Elements

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  bus
249
250 class Mux {
251     bus *i1, *i2, *i3, *o1;
252 public:
253     Mux(bus& a, bus& b, bus& sel, bus& w);
254     ~Mux(); // destructor
255     void evl();
256 };
257
258 class Tri {
259     bus *i1, *i2, *o1;
260 public:
261     Tri (bus& a, bus& tri, bus& w);
262     ~Tri(); // destructor
263     void evl ();
264 };
265
266 class Adder {
267     bus *i1, *i2, *i3, *o1, *o2;
268 public:
269     Adder(bus& a, bus& b, bus& ci, bus& co, bus& sum);
270     ~Adder();
271     void evl();
272 };
273
274 class Comparator {
275     bus *i1, *i2, *o1, *o2, *o3;
276 public:
277     Comparator(bus& a, bus& b, bus& lt, bus& eq, bus& gt);
278     ~Comparator();
279     void evl();
280 };
281
282 //class signExtend {
283 //class rightShift {
284
285 class nBitFunctionalRegister { ... };
```

classVectorPrimitives.h

Typical
Combinational RTL
elements

Combinational Elements

```
classVectorPrimitives.cpp  SeqDetector.cpp  utilityFunctions.h  SeqDetector.h
RTL Description (Global Scope)
1 #include "classVectorPrimitives.h"
2 #include <iostream>
3 #include <fstream>
4 #include <string>
5 #include <math.h>
6 using namespace std;
7
8 Mux::Mux (bus& a, bus& b, bus& sel, bus& w) : i1(&a), i2(&b), i3(&sel), o1(&w)
9 {
10     o1->fill('X');
11 }
12 void Mux::evl () {
13     if (*i3 == "0") *o1 = *i1; else *o1 = *i2;
14 }
15
16 Tri::Tri (bus& a, bus& tri, bus& w) : i1(&a), i2(&tri), o1(&w)
17 {
18     o1->fill('X');
19 }
20 void Tri::evl () {
21     if (*i2 == "1") *o1 = *i1; else o1->fill('Z');
22 }
23
24 Adder::Adder(bus& a, bus& b, bus& ci, bus& co, bus& sum) :
25     i1(&a), i2(&b), i3(&ci), o1(&sum), o2(&co)
26 {
27     o1->fill('X'); o2->fill('X');
28 }
29 void Adder::evl () {
30     bus result(i1->length() + 1);
31     result = *i1 + *i2 + *i3;
32     int leftIndex = result.length() - 1;
33     *o2 = result.at(leftIndex);
34     *o1 = result.range(leftIndex, 0);
35 }
36
```

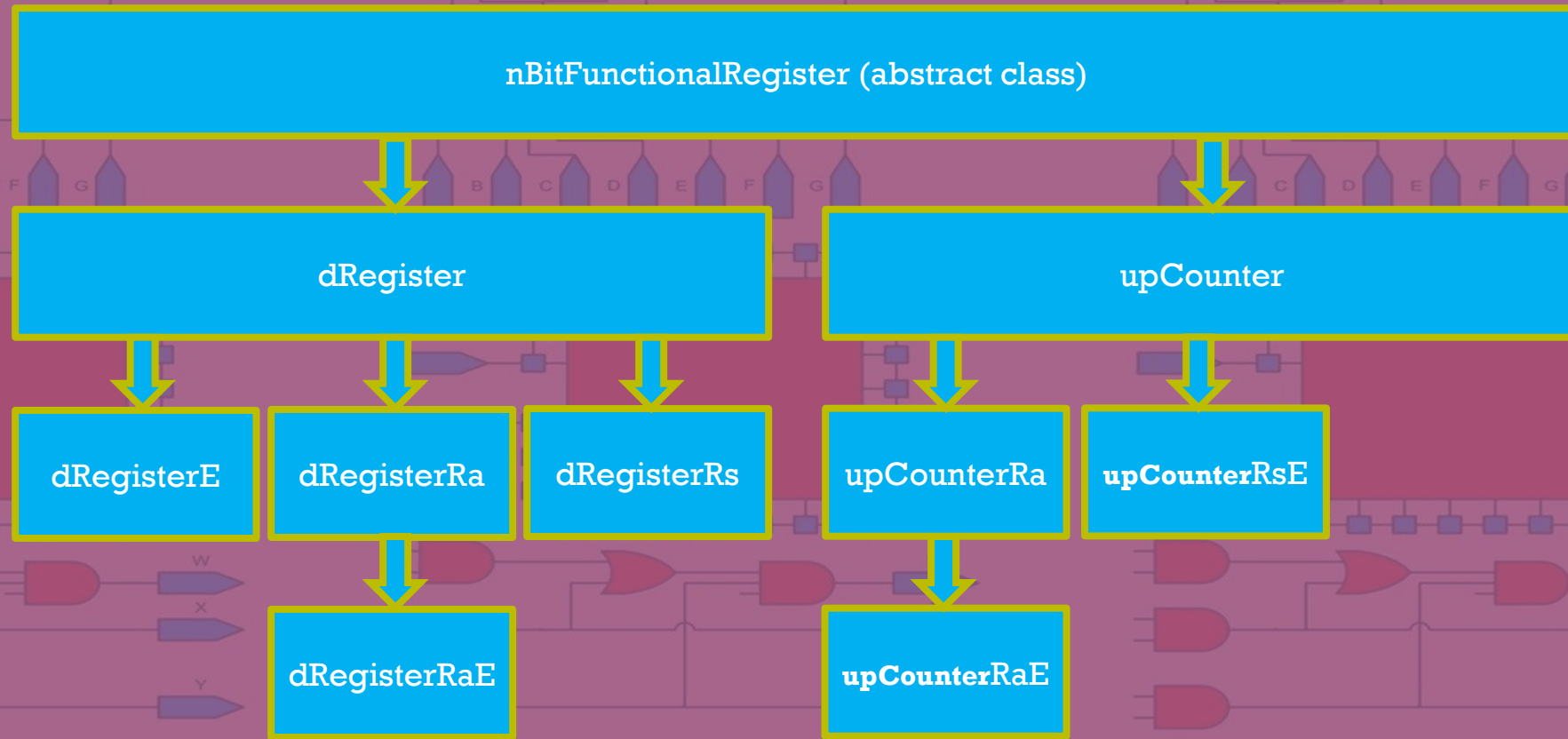
classVectorPrimitives.cpp

"+" operator is overloaded before

Registers and Counters

- Basic registers and counters are modeled in C/ C++
- Various functionalities
- Various clocking schemes
- Various resetting mechanisms
- Inheritance and Polymorphism is shown here

Registers and Counters



Functional Registers

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  (Global Scope)
285 class nBitFunctionalRegister {
286 public:
287     bus *d, *c, *q;
288     int size;
289     string rtype; // = "Register information";
290 public:
291     nBitFunctionalRegister (): size(0) {}
292     ~nBitFunctionalRegister () {}
293     void info (bus& D, bus& C, bus& Q, int& N, string& typ);
294     void init (string typ);
295     virtual void evl ()=0;
};

class dRegister : public nBitFunctionalRegister {
public:
    dRegister(bus& D, bus& C, bus& Q);
    ~dRegister();
    virtual void evl ();
};

class dRegisterE : public dRegister { //Enable
public:
    bus* e;
    dRegisterE (bus& D, bus& C, bus& E, bus& Q);
    ~dRegisterE ();
    void evl ();
};

class dRegisterRa : public dRegister { //Reset-asynch
public:
    bus* r;
    dRegisterRa(bus& D, bus& C, bus& R, bus& Q);
    ~dRegisterRa();
    virtual void evl ();
};
```

classVectorPrimitives.h

Initializing member variables.

Pure virtual method: Derived classes must define it. This is an abstract class because of this.

This is a default constructor. It must be since this is an abstract class.

The base class for all registers and counters

Functional Registers

```
classVectorPrimitives.cpp  utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
54 void nBitFunctionalRegister::info(bus& D, bus& C, bus& Q, int& N, string& typ){
55     D = *d;
56     C = *c;
57     Q = *q;
58     N = this->size;
59     typ.assign(rtype);
60 }
61 void nBitFunctionalRegister::init(string typ){
62     rtype = typ;
63 }
64
65 dRegister::dRegister(bus& di, bus& clk, bus& qo) {
66     d = &di;
67     c = &clk;
68     q = &qo;
69     size = q->length();
70     q->fill('X');
71 }
72 void dRegister::evl(){
73     if (c->at(0) == "P") *q = *d;
74 }
75
76 dRegisterE::dRegisterE (bus& di, bus& clk, bus& en, bus& qo)
77     : dRegister (di,clk,qo) {
78     e = &en;
79 }
80 void dRegisterE::evl(){
81     if (e->at(0) == "1") dRegister::evl();
82 }
83
84 dRegisterRa::dRegisterRa (bus& di, bus& clk, bus& rst, bus& qo){ ... }
88 void dRegisterRa::evl(){ ... }
92
93 dRegisterRaE::dRegisterRaE (bus& di, bus& clk, bus& rst, bus& en,
94     bus& qo){ ... }
97 void dRegisterRaE::evl(){ ... }
```

classVectorPrimitives.cpp

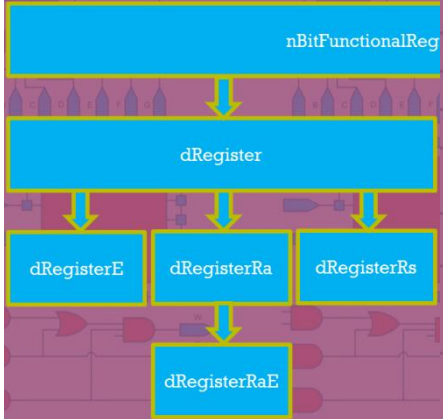
DRegister

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  X  utilityFunctions.cpp
RTL Description  (Global Scope)
285 class nBitFunctionalRegister {
286 public:
287     bus *d, *c, *q;
288     int size;
289     string rtype; // = "Register information";
290 public:
291     nBitFunctionalRegister () : size(0) {}
292     ~nBitFunctionalRegister () {}
293     void info (bus& D, bus& C, bus& Q, int& N, str
294     void init (string typ);
295     virtual void evl ()=0;
296 };
297
298 class dRegister : public nBitFunctionalRegister {
299 public:
300     dRegister(bus& D, bus& C, bus& Q);
301     ~dRegister();
302     virtual void evl ();
303 };
304
305 class dRegisterE : public dRegister { //Enable
306     bus* e;
307 public:
308     dRegisterE (bus& D, bus& C, bus& E, bus& Q)
309     ~dRegisterE ();
310     void evl ();
311 };
312
313 class dRegisterRa : public dRegister { //Reset-asynch
314 public:
315     bus* r;
316 public:
317     dRegisterRa(bus& D, bus& C, bus& R, bus& Q);
318     ~dRegisterRa();
319     virtual void evl ();
320 };
321
```

classVectorPrimitives.h

Virtual function. Can be used by derived classes as is or added to.

Derived from dRegister



DRegister

```
classVectorPrimitives.cpp  X utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
54 void nBitFunctionalRegister::info(bus& D, bus& C, bus& Q, int& N, string& typ){
55     D = *d;
56     C = *c;
57     Q = *q;
58     N= this->size;
59     typ.assign(rtype);
60 }
61 void nBitFunctionalRegister::init(string typ){
62     rtype = typ;
63 }
64
65 dRegister::dRegister(bus& di, bus& clk, bus& qo) {
66     d = &di;
67     c = &clk;
68     q = &qo;
69     size = q->length();
70     q->fill('X');
71 }
72
73 void dRegister::evl(){
74     if (c->at(0) == "P") *q = *d;
75 }
76
77 dRegisterE::dRegisterE (bus& di, bus& clk, bus& en, bus& qo)
78     : dRegister (di,clk,qo) {
79     e = &en;
80 }
81 void dRegisterE::evl(){
82     if (e->at(0) == "1") dRegister::evl();
83 }
84
85 dRegisterRa::dRegisterRa (bus& di, bus& clk, bus& rst, bus& qo) { ... }
86 void dRegisterRa::evl() { ... }
87
88 dRegisterRaE::dRegisterRaE (bus& di, bus& clk, bus& rst, bus& en,
89     bus& qo) { ... }
90 void dRegisterRaE::evl() { ... }
```

classVectorPrimitives.cpp

Assign register pointer
Set register size
Initialize the bus connected to the output

DRegisterE

```
classVectorPrimitives.cpp  X utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
54 void nBitFunctionalRegister::info(bus& D, bus& C, bus& Q, int& N, string& typ){
55     D = *d;
56     C = *c;
57     Q = *q;
58     N= this->size;
59     typ.assign(rtype);
60 }
61 void nBitFunctionalRegister::init(string typ){
62     rtype = typ;
63 }
64
65 dRegister::dRegister(bus& di, bus& clk, bus& qo) {
66     d = &di;
67     c = &clk;
68     q = &qo;
69     size = q->length();
70     q->fill('X');
71 }
72 void dRegister::evl(){
73     if (c->at(0) == "P") *q = *d;
74 }
75
76 dRegisterE::dRegisterE (bus& di, bus& clk, bus& en, bus& qo)
77     : dRegister (di,clk,qo) {
78     e = &en;
79 }
80 void dRegisterE::evl(){
81     if (e->at(0) == "1") dRegister::evl();
82 }
83
84 dRegisterRa::dRegisterRa (bus& di, bus& clk, bus& rst, bus& qo) { ... }
88 void dRegisterRa::evl() { ... }
92
93 dRegisterRaE::dRegisterRaE (bus& di, bus& clk, bus& rst, bus& en,
94     bus& qo) { ... }
97 void dRegisterRaE::evl() { ... }
```

classVectorPrimitives.cpp

dRegisterE::dRegisterE (bus& di, bus& clk, bus& en, bus& qo)
: dRegister (di,clk,qo) {
e = &en;

Dregister constructor is called
Enable port is assigned

void dRegisterE::evl(){
if (e->at(0) == "1") dRegister::evl();
}

DRegisterRS

```
classVectorPrimitives.cpp  X utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
84  dRegisterRa::dRegisterRa (bus& di, bus& clk, bus& rst, bus& qo)
85      : dRegister (di,clk,qo) {
86      }
87      r = &rst;
88  }
89  void dRegisterRa::evl(){
90      if (r->at(0) == "1") q->fill('0');
91      else dRegister::evl();
92  }
93  dRegisterRaE::dRegisterRaE (bus& di, bus& clk, bus& rst, bus& en,
94      bus& qo) : dRegisterRa (di,clk,rst,qo) {
95      }
96      e = &en;
97  }
98  void dRegisterRaE::evl(){
99      if (r->at(0) == "1") q->fill('0');
100     else if (e->at(0)=="1") dRegister::evl();
101 }
102 dRegisterRs::dRegisterRs (bus& di, bus& clk, bus& rst, bus& qo)
103     : dRegister (di,clk,qo) {
104     }
105     this->r = &rst;
106 }
107 void dRegisterRs::evl(){
108     if ((r->at(0) == "1" && (c->at(0) == "P"))
109     {
110         q->fill('0');
111     }
112     else dRegister::evl();
113 }
114 upCounter::upCounter (bus& di, bus& clk, bus& ld, bus& qo){...}
122 void upCounter::evl(){...}
131 }
132 upCounterRa::upCounterRa(bus& di, bus& clk, bus& rst, bus& ld,
133     bus& qo){...}
135 void upCounterRa::evl(){...}
148 }
```

classVectorPrimitives.cpp

dRegisterRs::dRegisterRs (bus& di, bus& clk, bus& rst, bus& qo)
: dRegister (di,clk,qo) {
this->r = &rst;
}
void dRegisterRs::evl(){
if ((r->at(0) == "1" && (c->at(0) == "P"))
{
q->fill('0');
}
else dRegister::evl();
}

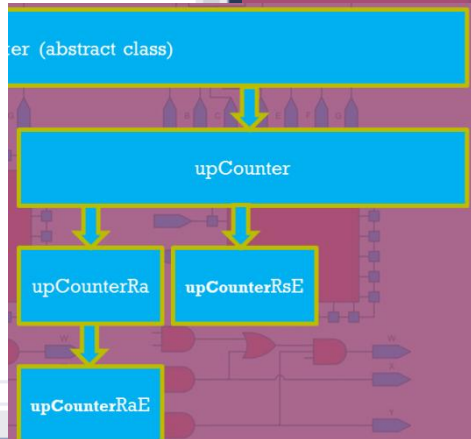
Dregister constructor is called
Enable port is assigned

UpCounter

```
classVectorPrimitives.cpp  classVectorFunctions.h  classVectorPrimitives.h*  utilityFunctions.cpp
RTL Description  (Global Scope)
321
322 class dRegisterRaE : public dRegisterRa { //Reset-asynch, Enable
323     bus* e;
324     public:
325     dRegisterRaE (bus& D, bus& C, bus& R, bus& E, bus& Q);
326     ~dRegisterRaE ();
327     void evl ();
328 };
329
330 class dRegisterRs : public dRegister {
331     bus* r;
332     public:
333     dRegisterRs (bus& D, bus& C, bus& R, bus& Q);
334     ~dRegisterRs ();
335     void evl ();
336 };
337
338 class upCounter : public nBitFunctionalRegister {
339     public:
340     bus* internalCount;
341     bus* l;
342     public:
343     upCounter (bus& D, bus& C, bus& L, bus& Q);
344     ~upCounter();
345     virtual void evl ();
346 };
347
348 class upCounterRsE : public upCounter { //Reset-asynch, Enable Count
349     bus* e;
350     bus* r;
351     public:
352     upCounterRsE (bus& D, bus& C, bus& R, bus& L, bus& E, bus& Q);
353     ~upCounterRsE ();
354     void evl ();
355 };
356
357
```

classVectorPrimitives.h

Counters add load input.



UpCounter

```
classVectorPrimitives.cpp  utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
114 upCounter::upCounter (bus& di, bus& clk, bus& ld, bus& qo) : l(&ld) {
115     d = &di;
116     c = &clk;
117     q = &qo;
118     size = d->length();
119     q->fill('X');
120     internalCount = new bus(size, '0');
121 }
122 void upCounter::evl(){
123     if (c->at(0)=="p") {
124         if (l->at(0) == "1") *internalCount = *d;
125         else {
126             *internalCount = *internalCount + "1";
127         }
128     }
129     *q = *internalCount;
130 }
131
132 upCounterRa::upCounterRa(bus& di, bus& clk, bus& rst, bus& ld,
133     bus& qo) : upCounter(di, clk, ld, qo), r(&rst) {
134 }
135 void upCounterRa::evl(){
136     if (r->at(0) == "1") {
137         q->fill('0');
138         internalCount->fill('0');
139     }
140     else upCounter::evl();
141 }
142
143 upCounterRsE::upCounterRsE(bus& di, bus& clk, bus& rst, bus& ld,
144     bus&en, bus& qo){ ... }
145 void upCounterRsE::evl(){ ... }
146
147
148 upCounterRaE::upCounterRaE(bus& di, bus& clk, bus& rst, bus& ld,
149     bus&en, bus&qo){ ... }
150 void upCounterRaE::evl(){ ... }
```

classVectorPrimitives.h

UpCounterRsE

```
LRUdatapath.cpp  LRUcontroller.cpp  classVectorPrimitives.h  classVectorPrimitives.cpp  X
RTL Description  upCounterRa  evl()
142
143 upCounterRsE::upCounterRsE(bus& di, bus& clk, bus& rst, bus& ld,
144   bus&en, bus& qo) : upCounter(di, clk, ld, qo), r(&rst), e(&en) {
145 }
146 void upCounterRsE::evl(){
147     if ((r->at(0) == "1" && (c->at(0) == "P"))
148     {
149         q->fill('0');
150         internalCount->fill('0');
151     }
152     else if (e->at(0) == "1") upCounter::evl();
153 }
154
155 upCounterRaE::upCounterRaE(bus& di, bus& clk, bus& rst, bus& ld,
156   bus&en, bus&qo) : upCounterRa(di, clk, rst, ld, qo), e(&en) {
157 }
158 void upCounterRaE::evl(){
159     if (r->at(0) == "1")
160     {
161         q->fill('0');
162         internalCount->fill('0');
163     }
164     else if (e->at(0) == "1") upCounter::evl();
165 }
166
167 Memory::Memory (bus& rst, bus& clk, bus& read, bus& write,
168   bus& Din, bus& AddrBus, bus& Dout) { ... }
183 Memory::~~Memory() { ... }
185
186 void Memory::init (const string& filename) { ... }
193 void Memory::dump (const string& filename) { ... }
202 void Memory::evl () { ... }
217
```

classVectorPrimitives.h

Memory Structure

```
LRUdatapath.cpp  LRUcontroller.cpp  classVectorPrimitives.h  classVectorPrimitives.cpp
RTL Description  (Global Scope)
356
357 class upCounterRa : public upCounter { //Reset-asynch
358 public:
359     bus* r;
360 public:
361     upCounterRa(bus& D, bus& C, bus& R, bus& L, bus& Q);
362     ~upCounterRa ();
363     virtual void evl ();
364 };
365
366 class upCounterRaE : public upCounterRa { //Reset-asynch, Enable Count
367     bus* e;
368 public:
369     upCounterRaE (bus& D, bus& C, bus& R, bus& L, bus& E, bus& Q);
370     ~upCounterRaE ();
371     void evl ();
372 };
373
374 class Memory{
375     bus *rst, *clk, *read, *write;
376     bus *Din, *AddrBus;
377     bus *Dout;
378     bus *mem;
379     int N;
380
381 public:
382     Memory (bus& rst, bus& clk, bus& read, bus& write,
383             bus& Din, bus& AddrBus, bus& Dout);
384     Memory() {};
385     ~Memory ();
386     void evl ();
387     void init (const string& filename);
388     void dump (const string& filename);
389 };
390
391 #endif
```

classVectorPrimitives.h

Use bus pointers for all memory ports

Memory Structure

```
LRUdatapath.cpp  LRUcontroller.cpp  classVectorPrimitives.h  classVectorPrimitives.cpp*  evl()
RTL Description  Memory
166
167 Memory::Memory (bus& rst, bus& clk, bus& read, bus& write,
168                 bus& Din, bus& AddrBus, bus& Dout) :
169     rst(&rst), read(&read), write(&write), clk(&clk), Din(&Din),
170     AddrBus(&AddrBus), Dout(&Dout)
171 {
172     this->write->fill('X');
173     this->Dout->fill('X');
174     int LEN = this->Dout->length();
175     N = int(pow(2, LEN));
176
177     mem = new bus[N];
178
179     for (int i=0; i < N; i++) {
180         mem[i].resize(LEN, '0');
181     }
182 }
183 Memory::~Memory() { ... }
184
185
186 void Memory::init (const string& filename) { ... }
187
188 void Memory::dump (const string& filename) { ... }
189
190
191 void Memory::evl () {
192     if (rst->at(0) == "1") {
193         for (int i = 0; i < N; i++) mem[i].fill('0');
194     }
195     else if (read->at(0) == "1") {
196         *Dout = mem[AddrBus->ival()];
197     }
198     else if (clk->at(0) == "p") {
199         if (write->at(0) == "1") {
200             mem[AddrBus->ival()] = *Din;
201         }
202     }
203 }
204
205
206
207
208
209
210
211
212
213
214
215
```

classVectorPrimitives.h

Memory resetting, read and write

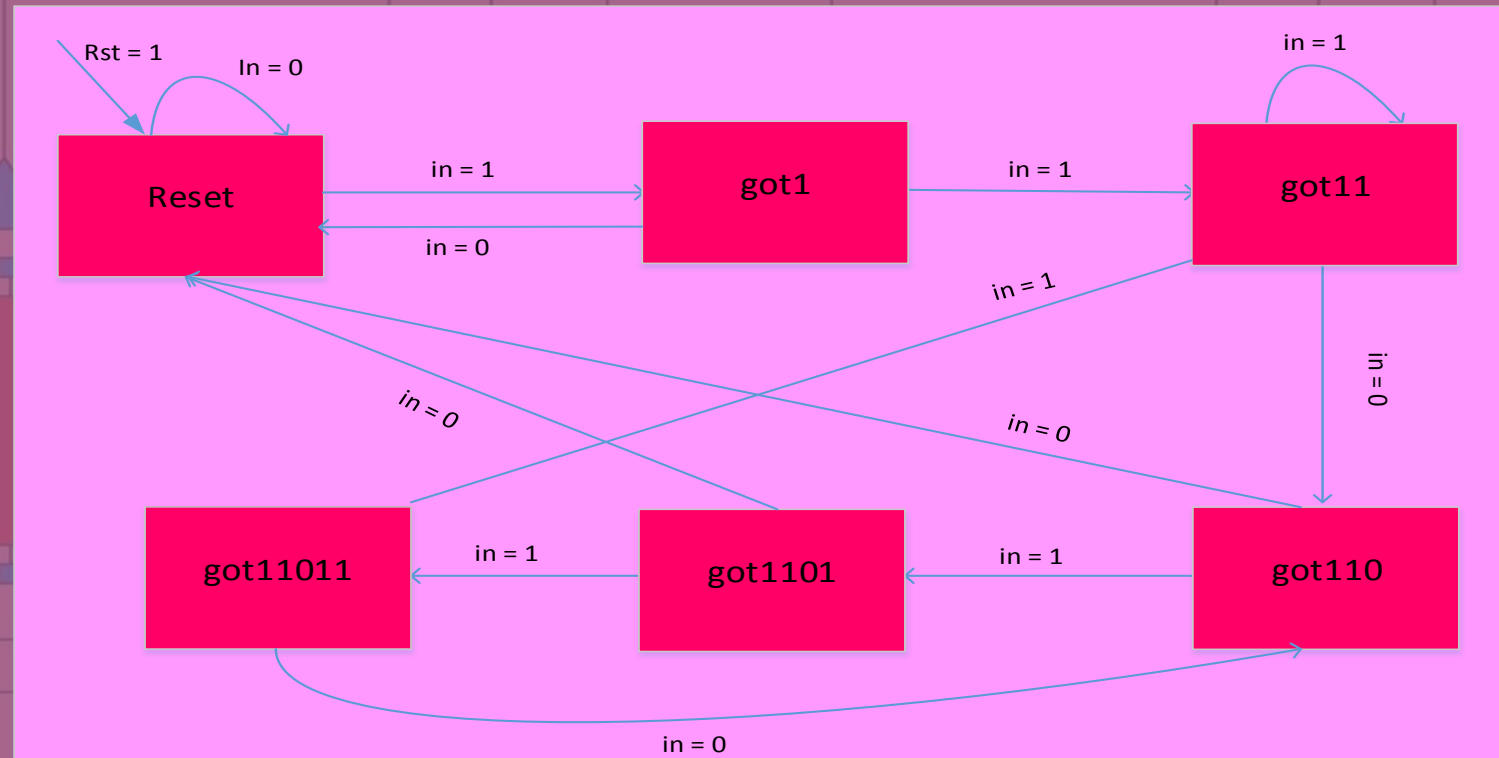
Memory Structure

```
LRUdatapath.cpp  LRUcontroller.cpp  classVectorPrimitives.h  classVectorPrimitives.cpp  ↗ ×
RTL Description  → upCounterRa  evl()
167 Memory::Memory (bus& rst, bus& clk, bus& read, bus& write,
168                 bus& Din, bus& AddrBus, bus& Dout) :
169     rst(&rst), read(&read), write(&write), clk(&clk), Din(&Din),
170     AddrBus(&AddrBus), Dout(&Dout)
171 {
172     this->write->fill('X');
173     this->Dout->fill('X');
174     int LEN = this->Dout->length();
175     N = int(pow(2, LEN));
176
177     mem = new bus[N];
178
179     for (int i=0; i < N; i++) {
180         mem[i].resize(LEN, '0');
181     }
182 }
183 Memory::~Memory() {
184 }
185
186 void Memory::init (const string& filename){
187     ifstream finp(filename);
188     for (int i = 0; i < N; i++) {
189         finp >> mem[i];
190         cout << mem[i] << "\n";
191     }
192 }
193 void Memory::dump (const string& filename){
194     ofstream fout(filename);
195     fout << "listing follows:\n";
196     cout << "listing follows:\n";
197     for (int i = 0; i < N; i++) {
198         fout << i << ": " << mem[i] << "\n";
199         cout << i << ": " << mem[i] << "\n";
200     }
201 }
202 void Memory::evl () { ... }
217
```

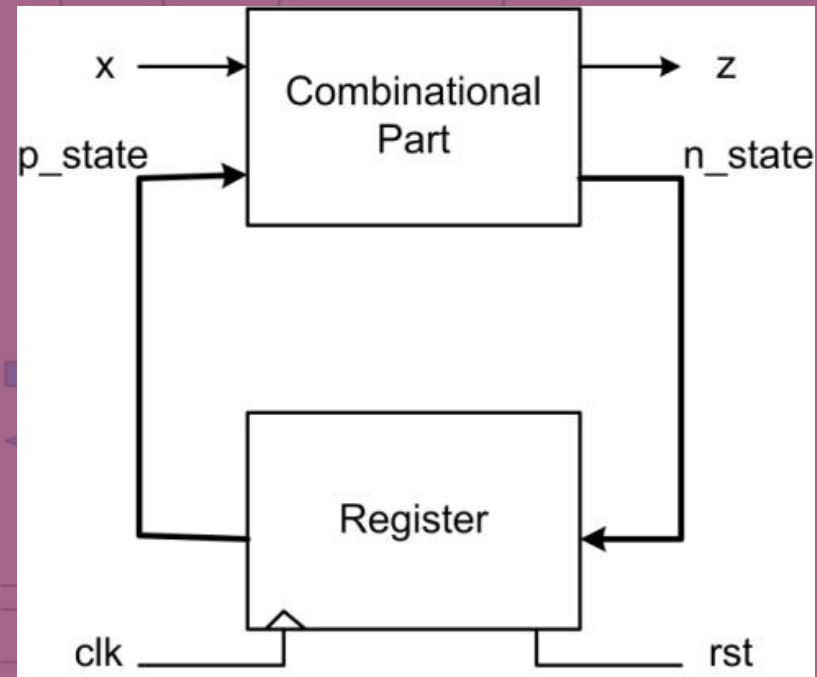
classVectorPrimitives.h

Use binary file passed to them and use overloaded "<<" and ">>"

Moore Sequence Detector (11011)



Moore Sequence Detector (11011)



Moore Sequence Detector (11011)

```
classVectorPrimitives.cpp  utilityFunctions.h  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
1  #include "classVectorPrimitives.h"
2  #include <string>
3  using namespace std;
4
5  class StateMachine{
6      bus *rst, *clk;
7      bus *in;
8      bus *out;
9      int Nstate, Pstate;
10     public:
11         StateMachine(bus& rst, bus& clk, bus& in, bus& out);
12         ~StateMachine();
13         void evl ();
14     };
15
```

SeqDetector.h

Moore Sequence Detector (11011)

```
SeqDetector.cpp  x  SeqDetector.h  classVectorPrimitives.cpp  classVectorPrimitives.h
RTL Description  (Global Scope)
3  StateMachine::StateMachine (bus& rst, bus& clk, bus& in, bus& out)
4  {
5      this->rst = &rst; this->clk = &clk; this->in = &in; this->out = &out;
6      Nstate = 0;
7      Pstate = 0;
8  }
9
10 void StateMachine::evl () {
11     *out = "0";
12
13     switch (Pstate){
14     case 0:
15         if(*in == "1") Nstate = 1;
16         else Nstate = 0; break;
17     case 1:
18         if (*in == "1") Nstate = 2;
19         else Nstate = 0; break;
20     case 2:
21         if(*in == "1") Nstate = 2;
22         else Nstate = 3; break;
23     case 3:
24         if(*in == "1") Nstate = 4;
25         else Nstate = 0; break;
26     case 4:
27         if(*in == "1") Nstate = 5;
28         else Nstate = 0; break;
29     case 5:
30         if (*in == "1") Nstate = 5;
31         else Nstate = 3; break;
32     }
33
34     if (*rst == "1") Pstate = 0;
35     else if (*clk == "P") Pstate = Nstate;
36
37     if (Pstate == 5) *out = "1";
38     else *out = "0";
39 }
```

SeqDetector.cpp

Switch statement
handle state transition

Sequential part
implementation

Moore Sequence Detector (11011)

```
SeqDetectorTB.cpp  classVectorPrimitives.cpp  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
1  #include "SeqDetector.h"
2  #include "classVectorFunctions.h"
3
4  int main ()
5  {
6      int ij;
7      bus clk, rst;
8      bus in;
9      bus out;
10
11     Statemachine* Statemachine1 = new Statemachine(rst, clk, in, out);
12
13     // Statemachine resetting
14     rst = "1";
15     Statemachine1->evl();
16     rst = "0";
17
18     do{
19         for ( int i =0; i<5; i++){
20             cout << "\n Enter 1 bits for the input: "; cin >> in;
21             clk = "p";
22             Statemachine1 -> evl();
23             cout << "\n" << out;
24         }
25         cout << "\n" << "Continue (0 or 1)?"; cin >> ij;
26     }while (ij >0);
27 }
28
29
```

SeqDetectorTB.cpp

RTL Level Modeling with C/C++

- **RTL Principles**

- Elements of datapath
- Elements of control unit

- **Bus Communications**

- **Utility functions**

- **Bus operations**

- Array Attributes

- Logical Operations

- Adding Operations

- Relational Operations

- IO Operations

- **Basic Elements of RTL**

- Combinational Elements

- Registers and Counters

- Functional register

- dRegister

- dRegisterE

- dRegisterRaE

- upCounter

- upCounterRaE

- Memory Structure

- Controller FSM

- Controller 11011

- **RTL design example: LRU**

- LRU structure

- LRU Modeling

- Controller

- Ordered instantiation

- **RTL design example 2: Exponential Circuit**

- Exponential Circuit Datapath

- Exponential Circuit Controller

LRU Updater

Assign queue positions to items based on frequency of their use

Before I9 is accessed

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

| | | | | | | | | | | | | | | | |
|----|-----|----|-----|----|----|----|-----|----|-----|----|-----|----|----|-----|----|
| P8 | P15 | P1 | P11 | P3 | P5 | P9 | P13 | P0 | P12 | P6 | P14 | P7 | P2 | P10 | P4 |
|----|-----|----|-----|----|----|----|-----|----|-----|----|-----|----|----|-----|----|

| | | | | | | | | | | | | | | | |
|----|----|-----|----|-----|----|----|-----|----|-----|----|-----|----|----|-----|----|
| P9 | P8 | P15 | P1 | P11 | P3 | P5 | P13 | P0 | P12 | P6 | P14 | P7 | P2 | P10 | P4 |
|----|----|-----|----|-----|----|----|-----|----|-----|----|-----|----|----|-----|----|

After I9 is accessed

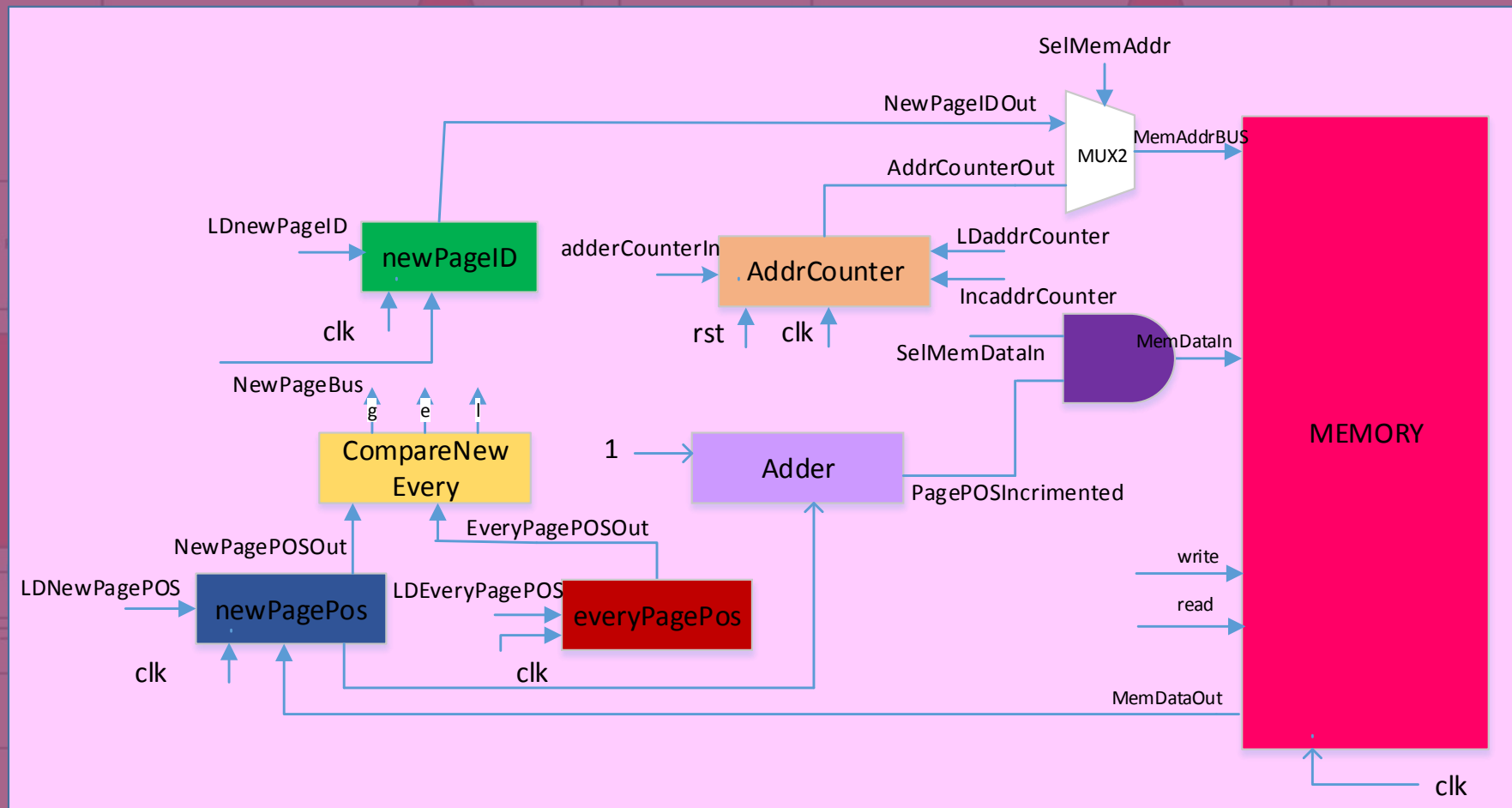
Queue Memory File

Before I9 is accessed

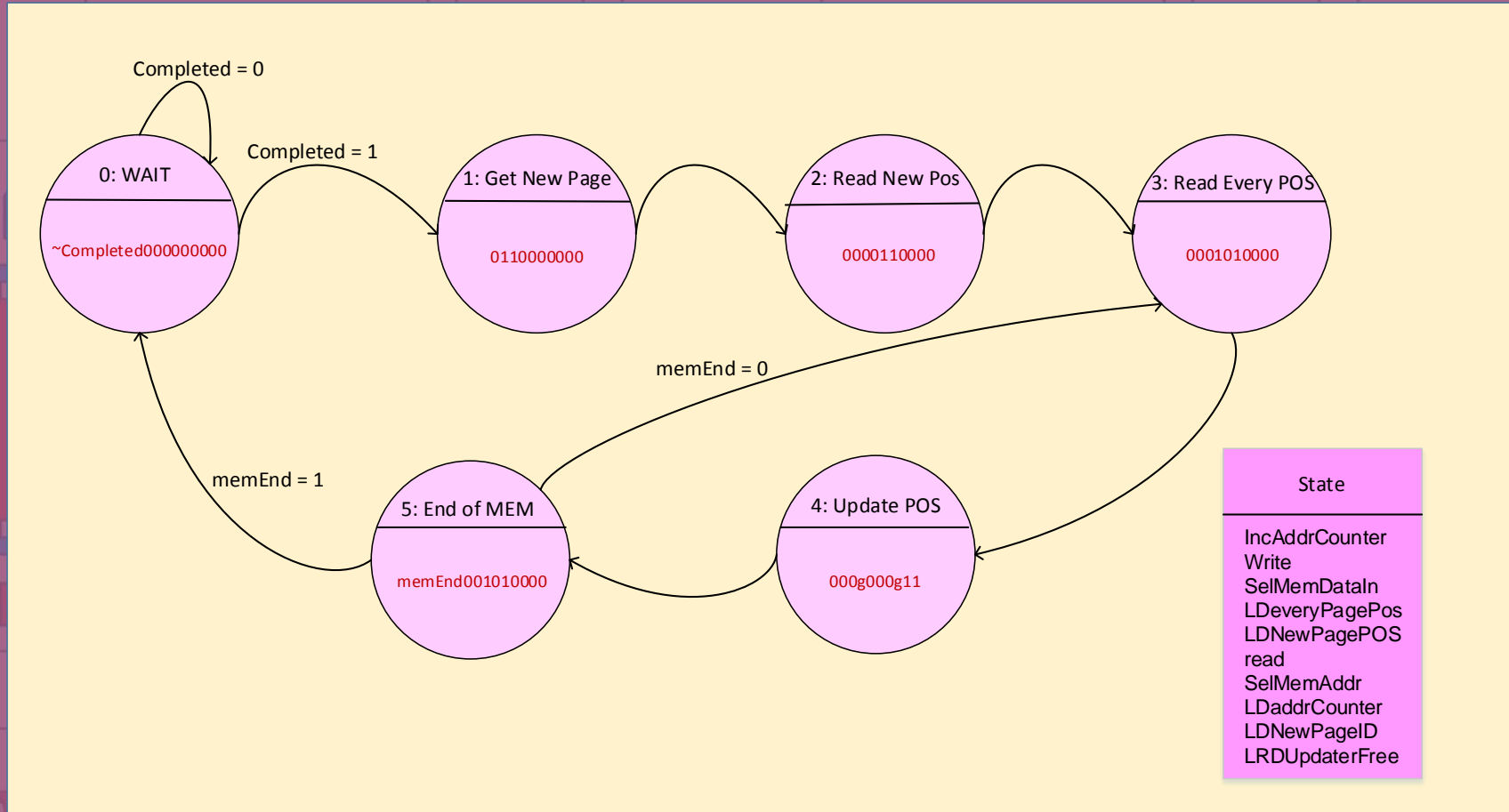
| | | |
|-----|----|-----|
| P0 | 8 | 8 |
| P1 | 2 | + 3 |
| P2 | 13 | 13 |
| P3 | 4 | + 5 |
| P4 | 15 | 15 |
| P5 | 5 | + 6 |
| P6 | 10 | 10 |
| P7 | 12 | 12 |
| P8 | 0 | + 1 |
| P9 | 6 | 0 |
| P10 | 14 | 14 |
| P11 | 3 | 4 |
| P12 | 9 | 9 |
| P13 | 7 | 7 |
| P14 | 11 | 11 |
| P15 | 1 | + 2 |

After I9 is accessed

LRU Updater Datapath



LRU Controller



LRU Controller

```
LRUcontroller.cpp  classVectorPrimitives.h  classVectorPrimitives.cpp  LRUcontroller.h  X
RTL Description  (Global Scope)
1  #include "classVectorPrimitives.h"
2  #include <string>
3  using namespace std;
4
5  class LRUcontroller{
6      bus *rst, *clk;
7      bus *LRUUpdaterFree, *Completed;
8      bus *l, *e, *g, *memEnd;
9      bus *LDnewPageId, *LDnewPagePos, *LDeveryPagePos;
10     bus *LDaddrCounter, *INCaddrCounter, *SElmemDataIn, *SElmemAddr;
11     bus *read, *write;
12     int Nstate, Pstate;
13     public:
14     LRUcontroller(bus& rst, bus& clk,
15         bus& LRUUpdaterFree, bus& Completed,
16         bus& l, bus& e, bus& g, bus& memEnd,
17         bus& LDnewPageId, bus& LDnewPagePos, bus& LDeveryPagePos,
18         bus& LDaddrCounter, bus& INCaddrCounter,
19         bus& SElmemDataIn, bus& SElmemAddr,
20         bus& read, bus& write);
21     ~LRUcontroller();
22     void evl ();
23 };
24
25
```

LRUcontroller.h

LRU Controller

```
LRUcontroller.cpp  classVectorPrimitives.cpp  LRUcontroller.h  LRUdatapath.h
RTL Description  → LRUcontroller  evl()

1  #include "LRUcontroller.h"
2
3  LRUcontroller::LRUcontroller (bus& rst, bus& clk,
4    bus& LRUUpdaterFree, bus& Completed,
5    bus& l, bus& e, bus& g, bus& memEnd,
6    bus& LDnewPageId, bus& LDnewPagePos, bus& LDeveryPagePos,
7    bus& LDaddrCounter, bus& INCaddrCounter,
8    bus& SELmemDataIn, bus& SELmemAddr,
9    bus& read, bus& write) :
10
11    rst(&rst), clk(&clk),
12    LRUUpdaterFree(&LRUUpdaterFree), Completed(&Completed),
13    l(&l), e(&e), g(&g), memEnd(&memEnd),
14    LDnewPageId(&LDnewPageId), LDnewPagePos(&LDnewPagePos),
15    LDeveryPagePos(&LDeveryPagePos),
16    LDaddrCounter(&LDaddrCounter), INCaddrCounter(&INCaddrCounter),
17    SELmemDataIn(&SELmemDataIn), SELmemAddr(&SELmemAddr),
18    read(&read), write(&write)
19  {
20    this->e->fill('0');
21    this->g->fill('0');
22    Nstate = 0;
23    Pstate = 0;
24  }
25
26  void LRUcontroller::evl () {
27    *LRUUpdaterFree = "1";
28    *LDnewPageId = "0";
29    *LDnewPagePos = "0";
30    *LDeveryPagePos = "0";
31    *LDaddrCounter = "0";
32    *INCaddrCounter = "0";
33    *SELmemDataIn = "0";
34    *SELmemAddr = "0";
35    *read = "0";
36    *write = "0";
37  }
```

LRUcontroller.cpp

LRU Controller

```
LRUcontroller.cpp  classVectorPrimitives.cpp  LRUcontroller.h  LRUdatapath.h
RTL Description  (Global Scope)
25
26 void LRUcontroller::ev1 () {
27     *LRUUpdaterFree = "1";
28     *LDnewPageId = "0";
29     *LDnewPagePos = "0";
30     *LDeveryPagePos = "0";
31     *LDaddrCounter = "0";
32     *INCaddrCounter = "0";
33     *SELMemDataIn = "0";
34     *SELMemAddr = "0";
35     *read = "0";
36     *write = "0";
37
38     switch (Pstate){
39         case 0: // Wait
40             if(*Completed == "1") Nstate = 1;
41             else Nstate = 0; break;
42         case 1: // Get new page Id
43             Nstate = 2; break;
44         case 2: // Read queue position of new page
45             Nstate = 3; break;
46         case 3: // Read queue position of other pages
47             Nstate = 4; break;
48         case 4: // Write updated position in mem
49             Nstate = 5; break;
50         case 5: // Back to 3 if mem end is not reached
51             if (*memEnd == "1") Nstate = 0;
52             else Nstate = 3; break;
53     }
54     switch (Pstate){
55         case 0: // Wait
56             if(*Completed == "1") *LRUUpdaterFree = "0";
57             break;
58         case 1: // Get new page Id
59             *LDnewPageId = "1";
60             *LDaddrCounter = "1";
61             *LRUUpdaterFree = "0";
```

LRUcontroller.cpp

LRU Controller

```
LRUcontroller.cpp  classVectorPrimitives.cpp  LRUcontroller.h  LRUdatapath.h
RTL Description  LRUcontroller  evl0
54  switch (Pstate){
55      case 0: // Wait
56          if(*Completed == "1") *LRUupdaterFree = "0";
57          break;
58      case 1: // Get new page Id
59          *LDnewPageId = "1";
60          *LDaddrCounter = "1";
61          *LRUupdaterFree = "0";
62          break;
63      case 2: // Read queue position of new page
64          *SElmemAddr = "0"; // newPageId on Addrbus
65          *read = "1";
66          *LDnewPagePos = "1";
67          *LRUupdaterFree = "0";
68          break;
69      case 3: // Read queue position of other pages
70          *SElmemAddr = "1"; // otherPageId on Addrbus
71          *read = "1";
72          *LDeveryPagePos = "1";
73          *LRUupdaterFree = "0";
74          break;
75      case 4: // Write updated position in mem, inc upcounter
76          if (*g == "1"){ // Write incremented value
77              *SElmemAddr = "1"; // Counter becomes address
78              *SElmemDataIn = "1";
79              *write = "1"; //
80          }
81          else if(*e == "1"){ // Write 0
82              *SElmemAddr = "1"; // Counter becomes address
83              *SElmemDataIn = "0";
84              *write = "1";
85          }
86          else {} // Keep the same
87          *INCaddrCounter = "1";
88          *LRUupdaterFree = "0";
89          break;
90      case 5: // Back to 3 if mem end is not reached
91          if (*memEnd == "1")
92              *LRUupdaterFree = "1";
93          else
94              *LRUupdaterFree = "0";
95          break;
96      }
}
```

LRUcontroller.cpp

LRU Design

```
LRUdesign.h  LRUdesign.cpp*  classVectorPrimitives.cpp  classVectorPrimitives.h  registersTB.cpp
RTL Description  (Global Scope)
51  switch (Pstate){
52  case 0: // Wait
53      if(*Completed == "1") *LRUUpdaterFree = "0";
54      break;
55  case 1: // Get new page Id
56      *LDnewPageId = "1";
57      *LDaddrCounter = "1";
58      *LRUUpdaterFree = "0";
59      break;
60  case 2: // Read queue position of new page
61      *SELMemAddr = "0"; // newPageId on Addrbus
62      *read = "1";
63      *LDnewPagePos = "1";
64      *LRUUpdaterFree = "0";
65      break;
66  case 3: // Read queue position of other pages
67      *SELMemAddr = "1"; // otherPageId on Addrbus
68      *read = "1";
69      *LDeveryPagePos = "1";
70      *LRUUpdaterFree = "0";
71      break;
72  case 4: // Write updated position in mem, inc upcounter
73      if (*g == "1"){ // Write incremented value
74          *SELMemAddr = "1"; // Counter becomes address
75          *SELMemDataIn = "1";
76          *write = "1"; //
77      }
78      else if(*e == "1"){ // Write 0
79          *SELMemAddr = "1"; // Counter becomes address
80          *SELMemDataIn = "0";
81          *write = "1";
82      }
83      else {} // Keep the same
84      *INCaddrCounter = "1";
85      *LRUUpdaterFree = "0";
86      break;
87  case 5: // Back to 3 if mem end is not reached
```

LRUdesign.cpp

LRU Design

```
LRUdesign.cpp  x LRUdesign.h  classVectorPrimitives.cpp  SeqDetector.h  classVectorPrimitives.h
RTL Description  (Global Scope)
91  case 4: // write in mem, increment upcounter;
92  if (*rst == "1") *LRUUpdaterFree = "1";
93  else if (*g == "1"){
94      *SELMemAddr = "1"; // newPageId on Addr Bus
95      *SELMemDataIn = "1";
96      *write = "1";
97      *LRUUpdaterFree = "0";
98      *INCAddrCounter = "1";
99  }
100 else if(*e == "1"){
101     *SELMemAddr = "1"; // ODIId on Addr Bus
102     *SELMemDataIn = "0";
103     *write = "1";
104     *INCAddrCounter = "1";
105     *LRUUpdaterFree = "0";
106 }
107 else{
108     *LRUUpdaterFree = "0";
109     *INCAddrCounter = "1";
110 }
111 break;
112 case 5: // compare upcounter with "0000"
113 if (*rst == "1") *LRUUpdaterFree = "1";
114 else if (*memEnd == "1"){
115     *LRUUpdaterFree = "1";
116 }
117 else *LRUUpdaterFree = "0";
118 break;
119 }
120 if (*rst == "1") Pstate = 0;
121 else if (*clk == "P") Pstate = Nstate;
122 }
123
```

LRUdesign.cpp

LRU Datapath

```
LRUcontroller.h  LRUdatapath.h  LRUdatapath.cpp  LRUdesignTB.cpp  LRUcontroller.cpp
RTL Description  LRUdatapath
class LRUdatapath{
5   bus *rst, *clk;
6   bus *newPageBus; // Input bus
7   bus *LRUUpdaterFree, *Completed;
8   bus *l, *e, *g, *memEnd;
9   bus *LDnewPageId, *LDnewPagePos, *LDeveryPagePos;
10  bus *LDaddrCounter, *INCaddrCounter, *SElmemDataIn, *SElmemAddr;
11  bus *read, *write;
12
13
14  dRegisterE* newPageId;
15  dRegisterE* newPagePos;
16  dRegisterE* everyPagePos;
17  Comparator* compareNewEvery;
18  Mux* MUX2;
19  upCounterRaE* addrCounter;
20  Memory* memory;
21
22  bus newPageIdOut; // Internal busses
23  bus newPagePosOut; bus everyPagePosOut;
24  bus pagePosIncremented; bus addrCounterOut;
25  bus addrCounterIn;
26  bus memAddrBus; // Memory busses
27  bus memDataBus; bus memDataOut;
28
29 public:
30  LRUdatapath(bus& rst_, bus& clk_, bus& newPageBus_,
31             bus& LRUUpdaterFree_, bus& Completed_,
32             bus& l_, bus& e_, bus& g_, bus& memEnd_,
33             bus& LDnewPageId_, bus& LDnewPagePos_, bus& LDeveryPagePos_,
34             bus& LDaddrCounter_, bus& INCaddrCounter_,
35             bus& SElmemDataIn_, bus& SElmemAddr_, bus& read_, bus& write_);
36  ~LRUdatapath();
37  void evl();
38  void evlMemory() { memory->evl(); }
39  void initMemory(string filename) { memory->init(filename); }
40  void dumpMemory(string filename) { memory->dump(filename); }
41  };
```

LRUdatapath.h

LRU Datapath

```
LRUcontroller.h  LRUdatapath.h  LRUdatapath.cpp  LRUdesignTB.cpp  LRUcontroller.cpp
RTL Description  (Global Scope)
4  LRUdatapath::LRUdatapath(bus& rst_, bus& clk_, bus& newPageBus_,
5  bus& LRUUpdaterFree_, bus& Completed_,
6  bus& l_, bus& e_, bus& g_, bus& memEnd_,
7  bus& LDnewPageId_, bus& LDnewPagePos_, bus& LDeveryPagePos_,
8  bus& LDaddrCounter_, bus& INCaddrCounter_,
9  bus& SELmemDataIn_, bus& SELmemAddr_,
10 bus& read_, bus& write_)
11 :
12 rst(&rst_), clk(&clk_),
13 newPageBus(&newPageBus_),
14 LRUUpdaterFree(&LRUUpdaterFree_), Completed(&Completed_),
15 l(&l_), e(&e_), g(&g_), memEnd(&memEnd_),
16 LDnewPageId(&LDnewPageId_), LDnewPagePos(&LDnewPagePos_),
17 LDeveryPagePos(&LDeveryPagePos_),
18 LDaddrCounter(&LDaddrCounter_), INCaddrCounter(&INCaddrCounter_),
19 SELmemDataIn(&SELmemDataIn_), SELmemAddr(&SELmemAddr_),
20 read(&read_), write(&write_)
21 {
22   newPageIdOut.resize(4, 'X'); // Internal busses:
23   newPagePosOut.resize(4, 'X');
24   newPagePosOut.resize(4, 'X');
25   everyPagePosOut.resize(4, 'X');
26   pagePosIncremented.resize(4, 'X');
27   addrCounterOut.resize(4, 'X');
28   addrCounterIn.resize(4, '0');
29   memAddrBus.resize(4, 'X'); // Memory busses:
30   memDataBus.resize(4, 'X'); memDataOut.resize(4, 'X');
31
32   newPageId = new dRegisterE(*newPageBus, *clk, *LDnewPageId, newPageIdOut);
33   newPagePos = new dRegisterE(memDataOut, *clk, *LDnewPagePos, newPagePosOut);
34   everyPagePos = new dRegisterE(memDataOut, *clk, *LDeveryPagePos, everyPagePosOut);
35   compareNewEvery = new Comparator(newPagePosOut, everyPagePosOut, *l, *e, *g);
36   MUX2 = new Mux(newPageIdOut, addrCounterOut, *SELmemAddr, memAddrBus);
37   addrCounter = new upCounterRaE(addrCounterIn, *clk, *rst, *LDaddrCounter,
38   *INCaddrCounter, addrCounterOut);
39   memory = new Memory(*rst, *clk, *read, *write, memDataBus, memAddrBus, memDataOut);
40 }
```

LRUdatapath.cpp

LRU Datapath

```
LRUcontroller.h  LRUdatapath.h  LRUdatapath.cpp  X  LRUdesignTB.cpp  LRUcontroller.cpp
RTL Description  (Global Scope)
3
4  LRUdatapath::LRUdatapath(bus& rst_, bus& clk_, bus& newPageBus_,
5    bus& LRUUpdaterFree_, bus& Completed_,
6    bus& l_, bus& e_, bus& g_, bus& memEnd_,
7    bus& LDnewPageId_, bus& LDnewPagePos_, bus& LDeveryPagePos_,
8    bus& LDaddrCounter_, bus& INCaddrCounter_,
9    bus& SELmemDataIn_, bus& SELmemAddr_,
10   bus& read_, bus& write_) { ... }
41
42 void LRUdatapath::evl()
43 {
44     newPageId->evl();
45     memDataBus = pagePosIncremented & *SELmemDataIn;
46     MUX2->evl();
47     memory->evl();
48     newPagePos->evl();
49     everyPagePos->evl();
50     pagePosIncremented = everyPagePosOut + "1";
51     addrCounter->evl();
52     compareNewEvery->evl();
53     *memEnd = ((addrCounterOut == "0000") ? "1" : "0");
54 }
55
56
```

LRUdatapath.cpp

LRU Testbench

```
LRUcontroller.cpp  LRUdatapath.cpp  LRUdesignTB.cpp  X  utilityFunctions.cpp
RTL Description  (Global Scope)  main()
1  #include "LRUcontroller.h"
2  #include "LRUdatapath.h"
3
4
5  int main ()
6  {
7      int ij;
8      string filename("priority.txt");
9
10     bus clk, rst;
11     bus newPageId(4);
12     bus LRUUpdaterFree, GETnewPageId;
13     bus l, e, g;
14     bus memEnd;
15     bus LDnewPageId;
16     bus LDnewPagePos, LDeveryPagePos;
17     bus LDaddrCounter, INCaddrCounter;
18     bus SELmemDataIn, SELmemAddr;
19     bus read, write;
20     bus co;
21     bus ci(1, '0');
22
23     LRUdatapath* datapath = new LRUdatapath(rst, clk, newPageId,
24     LRUUpdaterFree, GETnewPageId,
25     l, e, g, memEnd,
26     LDnewPageId, LDnewPagePos, LDeveryPagePos,
27     LDaddrCounter, INCaddrCounter,
28     SELmemDataIn, SELmemAddr,
29     read, write);
30     LRUcontroller* controller = new LRUcontroller(rst, clk,
31     LRUUpdaterFree, GETnewPageId,
32     l, e, g, memEnd,
33     LDnewPageId, LDnewPagePos, LDeveryPagePos,
34     LDaddrCounter, INCaddrCounter,
35     SELmemDataIn, SELmemAddr,
36     read, write);
37
```

LRUdesignTB.cpp

LRU Testbench

```
classVectorPrimitives.cpp  LRUcontroller.h  LRUpdatath.h  LRUpdatath.cpp  LRUdesignTB.cpp  X
RTL Description  (Global Scope)
37
38 // memory and controller resetting
39 rst = "1";
40 datapath->evlMemory();
41 controller->evl();
42 rst = "0";
43
44 // Initialize memory and dump
45 datapath -> initMemory (filename);
46 cout << "Initial memory contents: " << "\n";
47 datapath -> dumpMemory ("beforeFile.txt");
48
49 do{
50 cout << "Enter 4 bits for the accessed page number: "; cin >> newPageId;
51 GETnewPageId = "1";
52 do{
53     clk = "P";
54
55     datapath -> evl();
56     controller -> evl();
57
58 } while (LRUUpdaterFree == "0");
59 GETnewPageId = "0";
60
61 cout << "LRU memory contents after page " << newPageId << " is accessed:" << "\n";
62 datapath -> dumpMemory("afterFile.txt");
63 cout << "\n" << "Continue (0 or 1)?" << " "; cin >> ij;
64
65 }while (ij >0);
66
67 }
```

LRUdesignTB.cpp

LRU Output

```
C:\WINDOWS\system32\cmd.exe

Initial memory contents:
listing follows:
0: 0001
1: 0000
2: 0010
3: 1101
4: 0100
5: 0011
6: 0101
7: 1000
8: 1001
9: 0111
10: 1010
11: 1100
12: 1111
13: 0110
14: 1011
15: 1101
Enter 4 bits for the accessed page number: 1000
LRU memory contents after page 1000 is accessed:
listing follows:
0: 0010
1: 0001
2: 0011
3: 1101
4: 0101
5: 0100
6: 0110
7: 1001
8: 0000
9: 1000
10: 1010
11: 1100
12: 1111
13: 0111
14: 1011
15: 1101

Continue <0 or 1>?
```

RTL Level Modeling with C/C++

- RTL Principles

- Elements of datapath
- Elements of control unit

- Bus Communications

- Utility functions

- Bus operations

- Array Attributes

- Logical Operations

- Adding Operations

- Relational Operations

- IO Operations

- Basic Elements of RTL

- Combinational Elements

- Registers and Counters

- Functional register

- dRegister

- dRegisterE

- dRegisterRaE

- upCounter

- upCounterRaE

- Memory Structure

- Controller FSM

- Controller 11011

- RTL design example 1: LRU

- LRU structure

- LRU Modeling

- Controller

- Ordered instantiation

- RTL design example 2: Exponential Circuit

- Exponential Circuit Datapath

- Exponential Circuit Controller

RTL Example 2: Exponential Circuit

- The circuit calculates e^x using Taylor expansion.
- The input is an 8-bit fixed-point number.
- The output is a 10-bit fixed-point number including 2 integer bits and 8 fractional bits.
- The circuit receives x as the input with the pulse on the start signal.
- The calculation continues for 8 iterations.
- When the result becomes ready, done signal will be issued.

Input-output Range

- With 8 bit input size, x is in the range between 0.00000000 for the smallest and 0.11111111 for the largest value.
- Smallest output = 1 when e^0
- Largest output = 10.1010111 (2.68357) when e^1

Taylor Series

$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

```
e = 1;  
a = 1;  
for( i = 1; i < n; i++ )  
{  
    a = a * x * ( 1 / i );  
    e = e + a;  
}
```

Exponential Circuit Datapath

```
EXPdatapath.cpp  EXPcontroller.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential
class expDatapath
{
    bus *clk, *rst, *read;
    bus *loadExponent, *rstExponent;
    bus *loadTerm, *initTerm, *rstTerm;
    bus *selTableData;
    bus *rstResultReg, *initResultReg, *loadResultReg;
    bus *enCounter, *rstCounter, *initCounter;
    bus *x, *co, *addr, *result;

    dRegisterRaE* expReg;
    dRegisterRaE* termReg;
    dRegisterRaE* resultReg;

    Adder* Add;
    Multiplier* Mult;
    Mux* M1;
    Memory* fractionsMemory;
    upCounterRsE* indexCounter;

    // internal busses
    bus exponent;
    bus exponentInput;
    bus term;
    bus termInput;
    bus resultInput;
    bus addUpperInput;
    bus addResult;
    bus multUpperInput;
    bus multResult;
    bus tableData;
    bus memDataBus;
    bus countValue;
    bus initialCount;

    bus addCi, addCo, write;
    bus enableExponent;
    bus enableTermReg;
    bus enableResultReg;

public:

```

EXPdatapath.h

Third register for saving partial result

ROM for 1/i

1-a = a * x
2- multresult = a * 1/i

Exponential Circuit Datapath

```
EXPdatapath.cpp  EXPcontroller.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential (Global Scope)
44
45 public:
46   expDatapath(bus &clk, bus &rst, bus &read,
47             bus &loadExponent, bus &rstExponent,
48             bus &loadTerm, bus &initTerm, bus &rstTerm,
49             bus &selTableData,
50             bus &rstResultReg, bus &initResultReg, bus &loadResultReg,
51             bus &enCounter, bus &rstCounter, bus &initCounter,
52             bus &x, bus &co, bus &result);
53   ~expDatapath();
54   void evl();
55   void evlMemory() { fractionsMemory -> evl(); }
56   void initMemory (string filename) { fractionsMemory -> init(filename); }
57   void dumpMemory (string filename) { fractionsMemory -> dump(filename); }
58 };
59
60
61
```

EXPdatapath.h

Exponential Circuit Datapath

```
EXPdatapath.cpp  EXPcontroller.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential (Global Scope)
2
3 expDatapath::expDatapath(bus &clk_, bus &rst_, bus &read_,
4   bus &loadExponent_, bus &rstExponent_,
5   bus &loadTerm_, bus &initTerm_, bus &rstTerm_,
6   bus &selTableData_,
7   bus &rstResultReg_, bus &initResultReg_, bus &loadResultReg_,
8   bus &enCounter_, bus &rstCounter_, bus &initCounter_,
9   bus &x_, bus &co_, bus &result_)
10 :
11   clk(&clk_), rst(&rst_), read(&read_),
12   loadExponent(&loadExponent_), rstExponent(&rstExponent_),
13   loadTerm(&loadTerm_), initTerm(&initTerm_), rstTerm(&rstTerm_),
14   selTableData(&selTableData_),
15   rstResultReg(&rstResultReg_), initResultReg(&initResultReg_),
16   loadResultReg(&loadResultReg_),
17   enCounter(&enCounter_), rstCounter(&rstCounter_), initCounter(&initCounter_),
18   x(&x_), co(&co_), result(&result_)
19 {
20   // internal buses:
21   exponent.assign      ("XXXXXXXX");
22   exponentInput.assign ("XXXXXXXX");
23   term.assign         ("XXXXXXXX");
24   termInput.assign    ("XXXXXXXX");
25   resultInput.assign  ("XXXXXXXXXX");
26   addResult.assign    ("XXXXXXXXXX");
27   addUpperInput.assign("XXXXXXXXXX");
28   multResult.assign   ("XXXXXXXXXXXXXXXXXXXX");
29   multUpperInput.assign("XXXXXXXX");
30   tableData.assign    ("XXXXXXXXXX");
31   memDatabus.assign   ("XXXXXXXXXX");
32   countValue.assign   ("XXXX");
33   initialCount.assign  ("0001");
34
35   addCi = "0";
36
37   expReg = new dRegisterRaE (exponentInput, *clk, *rst, enableExponent, exponent);
38
39   termReg = new dRegisterRaE
40     (termInput, *clk, *rst, enableTermReg, term);
41
42   M1 = new Mux(tableData, exponent, *selTableData, multUpperInput);
```

EXPdatapath.cpp

Expand to their required size

Exponential Circuit Datapath

```
EXPdatapath.cpp  EXPcontroller.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential  (Global Scope)
34
35  addCi = "0";
36
37  expReg = new dRegisterRaE (exponentInput, *clk, *rst, enableExponent, exponent);
38
39  termReg = new dRegisterRaE
40      (termInput, *clk, *rst, enableTermReg, term);
41
42  M1 = new Mux(tableData, exponent, *selTableData, multUpperInput);
43
44  resultReg = new dRegisterRaE
45      (resultInput, *clk, *rst, enableResultReg, *result);
46
47  indexCounter = new upCounterRsE
48      (initialCount, *clk, *rstCounter, *initCounter, *enCounter, count);
49
50  fractionsMemory = new Memory
51      (*rst, *clk, *read, write, memDatabus, countValue, tableData, 16);
52
53  Mult = new Multiplier(term, multUpperInput, multResult);
54
55  Add = new Adder(addUpperInput, *result, addCi, addCo, addResult);
56
57 }
```

EXPdatapath.cpp

Some control signals are direct from controller, some is formed by oring several signals from the controller

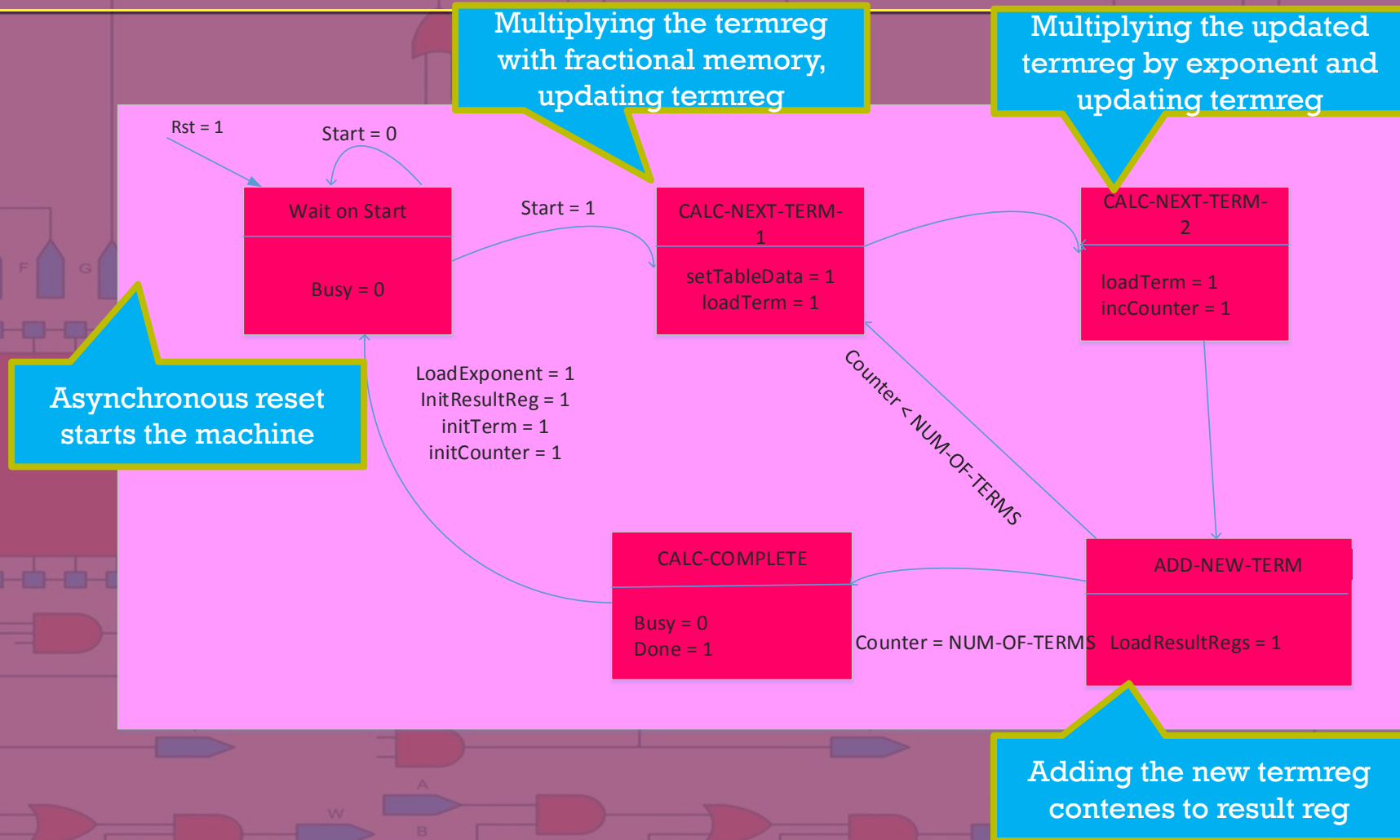
Exponential Circuit Datapath

```
EXPdatapath.cpp  EXPcontroller.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential      expDatapath      expDatapath(bus & clk_, bus & rst_, bus
57
58 void expDatapath::evl()
59 {
60     enableExponent = (*loadExponent | *rstExponent);
61     exponentInput = (*loadExponent == "1") ? *x :
62                   (*rstExponent == "1") ? "00000000" : "XXXXXXXX";
63     expReg -> evl();
64
65     fractionsMemory -> evl();
66
67     indexCounter -> evl();
68     *co = ((countValue < "1000")? "0": "1");
69
70     M1 -> evl();
71
72     Mult -> evl();
73
74     termInput = ( (*loadTerm == "1") ? multResult.range(15, 8) :
75                 (*initTerm == "1") ? "11111111" :
76                 (*rstTerm == "1")? "00000000" : "XXXXXXXX");
77     enableTermReg = (*loadTerm | *initTerm | *rstTerm );
78     termReg -> evl();
79
80     addUpperInput = ("00", term);
81     Add -> evl();
82
83     resultInput = ( (*loadResultReg == "1")? addResult :
84                   (*initResultReg == "1")? "0100000000" :
85                   (*rstResultReg == "1") ? "0000000000" : "XXXXXXXXXX");
86     enableResultReg = (*loadResultReg | *initResultReg | *rstResultReg);
87     resultReg -> evl();
88 }
89
```

EXPdatapath.cpp

The ordering of functions is important

Exponential Circuit Controller



Exponential Circuit Controller

```
EXPdatapath.cpp  EXPDesign.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h
Exponential (Global Scope)
1 #include "classVectorPrimitives.h"
2 #include <string>
3 using namespace std;
4
5 class expController{
6     bus *rst, *clk;
7     bus *start, *co, *read;
8     bus *loadExponent, *rstExponent, *loadTerm;
9     bus *initTerm, *rstTerm;
10    bus *selTableData;
11    bus *rstResultReg, *initResultReg, *loadResultReg;
12    bus *enCounter, *rstCounter, *initCounter;
13    bus *busy, *done;
14    int Nstate, Pstate;
15 public:
16     expController(bus& rst, bus& clk,
17                 bus& start, bus& co, bus &read,
18                 bus& loadExponent, bus& rstExponent,
19                 bus& loadTerm, bus& initTerm, bus& rstTerm,
20                 bus& selTableData,
21                 bus& rstResultReg, bus& initResultReg, bus& loadResultReg,
22                 bus& enCounter, bus& rstCounter, bus& initCounter,
23                 bus& busy, bus& done);
24     ~expController();
25     void evl ();
26 };
27
28
```

EXPcontroller.h

Exponential Circuit Controller

```
EXPdatapath.h  EXPcontroller.h  EXPDesign.h  EXPdatapath.cpp  EXPcontroller.cpp  - X
Exponential  -> expController  evl()

2
3  expController::expController (bus& rst_, bus& clk_,
4  bus& start_, bus& co_, bus& read_,
5  bus& loadExponent_, bus& rstExponent_,
6  bus& loadTerm_, bus& initTerm_, bus& rstTerm_,
7  bus& selTableData_,
8  bus& rstResultReg_, bus& initResultReg_, bus& loadResultReg_,
9  bus& enCounter_, bus& rstCounter_,
10 bus& initCounter_, bus& busy_, bus& done_)
11 :
12   rst(&rst_), clk(&clk_),
13   start(&start_), co(&co_), read(&read_),
14   loadExponent(&loadExponent_), rstExponent(&rstExponent_),
15   loadTerm(&loadTerm_), initTerm(&initTerm_), rstTerm(&rstTerm_),
16   selTableData(&selTableData_),
17   rstResultReg(&rstResultReg_), initResultReg(&initResultReg_),
18   loadResultReg(&loadResultReg_),
19   enCounter(&enCounter_), rstCounter(&rstCounter_), initCounter(&initCounter_),
20   busy(&busy_), done(&done_)
21 {
22     Nstate = 0;
23     Pstate = 0;
24 }
25
26 void expController::evl () {
27     *loadExponent = "0";
28     *rstExponent = "0";
29     *loadTerm = "0";
30     *initTerm = "0";
31     *rstTerm = "0";
32     *selTableData = "0";
33     *rstResultReg = "0";
34     *initResultReg = "0";
35     *loadResultReg = "0";
36     *enCounter = "0";
37     *rstCounter = "0";
38     *initCounter = "0";
39     *busy = "0";
40     *done = "0";
41     *read = "0";
42 }
```

EXPcontroller.cpp

Control signals are set to inactive values

Exponential Circuit Controller

```
EXPdatapath.h  EXPcontroller.h  EXPDesign.h  EXPdatapath.cpp  EXPcontroller.cpp  evl0
Exponential  expController
26 void expController::evl () {
27     *loadExponent = "0";
28     *rstExponent = "0";
29     *loadTerm = "0";
30     *initTerm = "0";
31     *rstTerm = "0";
32     *selTableData = "0";
33     *rstResultReg = "0";
34     *initResultReg = "0";
35     *loadResultReg = "0";
36     *enCounter = "0";
37     *rstCounter = "0";
38     *initCounter = "0";
39     *busy = "0";
40     *done = "0";
41     *read = "0";
42
43     switch (Pstate){
44     case 0: //INITIALIZE
45         if( *start == "0" ) Nstate = 0;
46         else Nstate = 1;
47         break;
48     case 1: //WAIT_ON_START
49         if( *start == "0" ) Nstate = 2;
50         else Nstate = 1;
51         break;
52     case 2: //CALC_NEXT_TERM_1
53         Nstate = 3;
54         break;
55     case 3: //CALC_NEXT_TERM_2
56         Nstate = 4;
57         break;
58     case 4: //ADD_NEW_TERM
59         if( *co == "0" ) Nstate = 2;
60         else Nstate = 5;
61         break;
62     case 5: //CALC_COMPLETE: begin
63         if(*start == "0") Nstate = 0;
64         else Nstate = 1;
65         break;
66     }
}
```

EXPcontroller.cpp

Switch Case for setting Nstate

Exponential Circuit Controller

```
EXPdatapath.h  EXPcontroller.h  EXPDesign.h  EXPdatapath.cpp  EXPcontroller.cpp  ev10
Exponential
67  switch (Pstate){
68  case 0 : //INITIALIZE
69      *rstExponent = "1"; *rstTerm = "1";
70      *rstResultReg = "1"; *rstCounter = "1";
71      break;
72  case 1: //WAIT_ON_START
73      *loadExponent = "1";
74      *initResultReg = "1";
75      *initTerm = "1";
76      *initCounter = "1";
77      *enCounter = "1";
78      break;
79  case 2: //CALC_NEXT_TERM_1
80      *busy = "1";
81      *selTableData = "1";
82      *loadTerm = "1";
83      break;
84  case 3 : //CALC_NEXT_TERM_2
85      *read = "1";
86      *busy = "1";
87      *loadTerm = "1";
88      *enCounter = "1";
89      break;
90  case 4: //ADD_NEW_TERM
91      *loadResultReg = "1";
92      *busy = "1";
93      break;
94  case 5: //CALC_COMPLETE
95      *done = "1";
96      *busy = "0";
97      break;
98
99  if (*rst == "1") Pstate = 0;
100 else if (*clk == "P") Pstate = Nstate;
101 }
102
```

EXPcontroller.cpp

Switch for issuing control signals

Getting pstate ready for the next clock cycle

Exponential Circuit Design

```
EXPDesign.cpp  EXPDesignTB.cpp  EXPdatapath.h  EXPcontroller.h  EXPDesign.h  X
Exponential (Global Scope)
1 #include "expController.h"
2 #include "expDatapath.h"
3
4 class expDesign
5 {
6     bus *clk, *rst, *start;
7     bus *x;
8     bus *result;
9     bus *busy, *done;
10
11     // internal nodes
12     bus loadExponent, rstExponent;
13     bus loadTerm, initTerm, rstTerm;
14     bus selTableData;
15     bus rstResultReg, initResultReg, loadResultReg;
16     bus enCounter, rstCounter, initCounter;
17     bus co, read;
18
19     // module
20     expDatapath* DP;
21     expController* CT;
22 public:
23     expDesign ( bus &clk, bus &rst, bus &start, bus &x,
24               bus &result, bus &busy, bus &done);
25     ~expDesign();
26     void evl();
27     void initialize (const string& filename);
28 };
29
```

EXPDesign.h

Controller and datapath class pointers

Exponential Circuit Design

```
EXPdatapath.cpp  EXPdesignTB.cpp  EXPdatapath.h  EXPcontroller.h  EXPDesign.cpp  ↵ ×
Exponential (Global Scope)
1  #include "expDesign.h"
2
3  expDesign::expDesign(bus &clk_, bus &rst_, bus &start_, bus &x_, bus &result_,
4  bus &busy_, bus &done_) :
5  clk(&clk_), rst(&rst_), start(&start_), x(&x_), result(&result_),
6  busy(&busy_), done(&done_)
7  {
8  DP = new expDatapath(*clk_, *rst_, read,
9  loadExponent, rstExponent, loadTerm, initTerm, rstTerm,
10 selTableData,
11 rstResultReg, initResultReg, loadResultReg,
12 enCounter, rstCounter, initCounter,
13 *x, co,*result);
14 CT = new expController (*rst_, *clk_, *start_, co, read,
15 loadExponent, rstExponent, loadTerm, initTerm, rstTerm,
16 selTableData,
17 rstResultReg, initResultReg, loadResultReg,
18 enCounter, rstCounter, initCounter,
19 *busy, *done);
20 }
21 void expDesign::evl()
22 {
23 DP -> evl();
24 CT -> evl();
25 }
26 void expDesign::initialize(const string& filename)
27 {
28 //resetting
29 *rst = "1";
30 DP -> evlMemory();
31 DP -> evl();
32 CT -> evl();
33 *rst = "0";
34 //Initialize fractionsMemory and dump
35 DP -> initMemory (filename);
36 DP -> dumpMemory ("beforeFile.txt");
37 }
38
39
```

EXPcontroller.cpp

void expDesign::initialize(const string& filename)
{
//resetting
*rst = "1";
DP -> evlMemory();
DP -> evl();
CT -> evl();
*rst = "0";
//Initialize fractionsMemory and dump
DP -> initMemory (filename);
DP -> dumpMemory ("beforeFile.txt");
}

Resets the memory and initializes datapath and controller units

Exponential Circuit Design

```
EXPDesign.h  EXPdatapath.cpp  EXPcontroller.cpp  EXPDesign.cpp  EXPdesignTB.cpp  + X
Exponential  (Global Scope)
1  #include "expDesign.h"
2
3  int main ()
4  {
5      int ij = 0;
6
7      string filename("coefficient.txt");
8
9      bus clk, rst, start, done, busy;
10     bus x(8);
11     bus result(10);
12
13     // module instantiation
14     expDesign *EXP = new expDesign(clk, rst, start, x, result, busy, done);
15
16     EXP -> initialize(filename);
17
18     do {
19         cout << "Enter 8 bits for input data: "; cin >> x;
20         cout << endl;
21         start = "1";
22         do{
23             clk = "p";
24             EXP -> evl();
25             start = "0";
26         } while (done == "0");
27         cout << "exp^(0." << x << ") = "
28             << result.range(9,8)<< "."<< result.range(7,0) << "\n";
29         cout << endl << "exp^( " << fval(x) << ") = "
30             << double(result.range(9,8).ival()) + fval(result.range(7,0)) << "\n";
31         cout << "\n" << "Continue (0 or 1)?";
32         cin >> ij;
33     } while (ij >0);
34 }
35
36
```

EXPdesignTB.cpp

Exponential Circuit Design

```
C:\WINDOWS\system32\cmd.exe
Enter 8 bits for input data: 00000000
exp^(0.00000000) = 01.00000000
exp^(0) = 1
Continue (0 or 1)?1
Enter 8 bits for input data: 11111111
exp^(0.11111111) = 10.10101111
exp^(0.996094) = 2.68359
Continue (0 or 1)?
```

Summary

- Developing utilities for bus classes
- Utilities are used for developing components for design of circuit at the RTL
- Ordering the operations is a key point to correct simulation
- Complete RTL Design: LRU
- Complete RTL Design: Exponential Circuit